

Asymptotic analysis of high-frequency acoustic modes in rapidly rotating stars

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ABSTRACT

Context. The asteroseismology of rapidly rotating pulsating stars is hindered by our poor knowledge of the effect of the rotation on the oscillation properties.

Aims. Here we present an asymptotic analysis of high-frequency acoustic modes in rapidly rotating stars.

Methods. We study the Hamiltonian dynamics of acoustic rays in uniformly rotating polytropic stars and show that the phase space structure has a mixed character, regions of chaotic trajectories coexisting with stable structures like island chains or invariant tori. In order to interpret the ray dynamics in terms of acoustic mode properties, we then use tools and concepts developed in the context of quantum physics.

Results. Accordingly, the high-frequency acoustic spectrum is a superposition of frequency subsets associated with dynamically independent phase space regions. The sub-spectra associated with stable structures are regular and can be modelled through EBK quantization methods while those associated with chaotic regions are irregular but with generic statistical properties. The results of this asymptotic analysis are successfully confronted with the properties of numerically computed high-frequency acoustic modes. The implications for the asteroseismology of rapidly rotating stars are discussed.

Key words. Hydrodynamics - Waves - Chaos - Stars: oscillations - Stars: rotation

1. Introduction

Interpreting the oscillation spectra of rapidly rotating stars is a long standing unsolved problem of asteroseismology. It so far prevented to directly probe the interior of stars in large fractions of the HR diagram, mostly in the range of intermediate and massive stars. Important progresses are nevertheless expected from the current spatial seismology missions (in particular COROT and KEPLER) as well as from recent modelling efforts on the effect of rotation on stellar oscillations. On the modelling side, new numerical codes have been able to accurately compute oscillation frequencies in significantly centrifugally distorted polytropic models of stars (Lignières et al., 2006; Reese et al., 2006) and are being extended to more realistic models (Reese et al., 2009). In particular the previous calculations based on perturbative methods were shown to be inadequate for these stars (Reese et al., 2006; Lovekin & Deupree, 2008). Nevertheless, interpreting the data requires an understanding of the mode properties that goes far beyond the accurate computation of frequencies. Indeed, the necessary identification of the observed frequencies with theoretical frequencies is a largely underconstrained problem which requires a priori information on the spectrum to be successful. The knowledge of the structure of the frequency spectrum is of primary importance in this context. For slowly rotating pulsating stars, this structure is characterized by regular frequency patterns which can be analytically derived from an asymptotic theory of the high-frequency acoustic modes.

Until recently, the asymptotic structure of the frequency spectrum of rapidly rotating stars was completely unknown. Our first calculations of low degree ($\ell = 0 - 7$) and low order ($n = 1 - 10$) acoustic axisymmetric modes in centrifugally distorted polytropic stars (Lignières et al., 2006) have revealed the presence of regular frequency patterns similar albeit different from those of spherically symmetric stars. This was confirmed using more realistic calculations including the Coriolis force and was also extended to non-axisymmetric and higher-frequency modes (Reese et al., 2008). The analogy with the non-rotating case suggests an asymptotic analysis could model these empirical regular patterns.

The asymptotic analysis presented in this paper is based on the acoustic ray dynamics. This approach can be viewed as a natural extension of the asymptotic analysis developed for non-rotating stars (Vandakurov, 1967; Tassoul, 1980, 1990; Deubner & Gough, 1984; Roxburgh & Vorontsov, 2000). In this case, spherical symmetry enables to reduce the initial 3D boundary value problem to a 1D boundary value problem in the radial direction. Asymptotic solutions of this 1D boundary value problem can then be obtained using a short-wavelength approximation which consists in looking for wave-like solutions under the assumption that their wavelength is much smaller than the typical lengthscale of the background medium. As rotation breaks the spherical symmetry, the eigenmodes are no longer separable in the latitudinal and radial directions and the 3D boundary value problem of acoustic modes in rapidly rotating stars can not be reduced to a 1D boundary value problem. Thus, the short-wavelength approximation is directly applied to the 3D

equations governing linear adiabatic stellar perturbations. This leads to an acoustic ray model which describes the propagation of locally plane waves. Since we are concerned by oscillation modes, the main issue of an asymptotic analysis based on ray dynamics is to construct standing waves solutions from the short-wavelength propagating waves described by the acoustic rays.

The short-wavelength approximation of wave equations is standard in physics, best known examples being the geometrical optics limit of electromagnetic waves or the classical limit of quantum mechanics. We shall see that similarly to these cases the acoustic rays in stars can be described as trajectories of a particle in the framework of classical Hamiltonian mechanics. As is well known in quantum physics (Gutzwiller, 1990; Ott, 1993), the issue of construction modes from the ray dynamics depends crucially on the nature of this Hamiltonian motion.

Indeed, Hamiltonian systems can have one of two very different behaviors. If there are enough constants of motion, the dynamics is integrable, and trajectories organize themselves in families on well-defined phase space structures. In contrast, chaotic systems display exponential divergence of nearby trajectories, and a typical orbit is ergodic in phase space. The modes constructed from these different dynamics are markedly different. For integrable systems, the eigenfrequency spectrum can be described by a function of N integers, N being the number of degrees of freedom of the system. In contrast, the spectrum of chaotic systems shows no such regularities. However, the spectrum possesses generic statistical properties which can be predicted. In the last thirty years, the field called quantum chaos has developed concepts and methods to relate non-integrable ray dynamics to properties of the associated quantum systems (and more generally wave systems).

We shall see that the acoustic ray dynamics in rotating stars undergoes a transition from an integrable system at zero rotation to a mixed system, that is a system with a phase space containing integrable and chaotic regions, at high rotation. The acoustic ray dynamics of rotating stars being non-integrable, we are led to use quantum chaos theory to predict the asymptotic properties of acoustic modes.

In the following, we shall describe in detail the ray dynamics, the predictions on the modes properties and their validation through a comparison with numerically computed acoustic modes. But, before going into the technical details of this analysis, we would like to summarize our results, giving emphasis to those of practical interest for mode identification. These results have been obtained for a sequence of uniformly rotating polytropic models, but we expect them to be qualitatively correct for a wider range of models. At high rotation rates, the frequency spectrum can be generically described as the superposition of an irregular frequency subset and of various regular frequency subsets each showing specific patterns. This spectrum structure is significantly more complex than in the spherical case where all acoustic frequencies follow the same organization such as given by Tassoul's formula (Tassoul, 1980). However, in the observed spectrum, only two frequency subsets are expected to be dominant. One subset (the subset of island modes) shows regular patterns similar albeit different to those found in non-rotating stars (it corresponds to the modes subset studied by Lignières et al. (2006); Reese et al. (2008)). These modes are associated with rays whose dynamics is near-integrable and consequently asymptotic formulas describing their regular patterns can be derived. The second frequency subset (the subset of chaotic modes) is associated with chaotic rays. Although it does not follow a regular pattern, specific statistical properties of this frequency subset can be predicted. Besides, the asymptotic

analysis provides an estimate of the proportion of mode in each subset. The transition from the non-rotating case occurs as follows: At moderate rotation, the regular subset of island modes is superposed to another regular subset (the subset of whispering gallery modes) which is a direct continuation of the non-rotating spectrum. At this stage, chaotic modes are rare and difficult to observe. As rotation increases, the number of chaotic modes increases while whispering gallery modes become less and less visible. Obviously, such a priori informations on the frequency spectrum should be of practical interest for the mode identification. One should however keep in mind that the asymptotic analysis is not supposed to be accurate for the lowest frequency p-modes. Although a detailed study of the asymptotic analysis limit of validity has not been performed yet, numerical results indicate that the regular patterns are quite accurate down to 5th radial order (see Lignières et al., 2006; Reese, 2007). At lower radial orders, the asymptotic mode classification in different subsets could still be applicable.

The paper is organized as follows: The equations governing the star model, the small perturbations about this model, the short-wavelength approximation of these perturbations and the ray model for progressive acoustic waves are presented in Section 2. A detailed numerical study of the acoustic ray dynamics has been conducted for uniformly rotating polytropic models of stars.

The results are analyzed in Section 3 using Poincaré Surface of Section, a standard tool to visualize the phase space structure. It shows that, as rotation increases, the dynamics undergoes a transition from integrability (at zero rotation) to a mixed state where parts of the phase space display integrable behaviour and while other parts are chaotic.

We then relate the acoustic ray dynamics to the asymptotic properties of the acoustic modes (Section 4). We first summarize the results obtained in the context of quantum physics distinguishing the cases where the Hamiltonian system is integrable, fully chaotic or of mixed nature. In accordance with this theory, we show that the asymptotic acoustic spectrum of the uniformly rotating polytropic models of stars is a superposition of regular frequency patterns and irregular frequency subsets respectively associated with near-integrable and chaotic phase space regions. The averaged number of modes associated with each phase space regions depends directly on its volume (in phase space). These predictions are then successfully confronted with the actual properties of high-frequency acoustic modes computed for a particular fast rotating stellar model.

In Section 5, after a critical discussion of the assumptions of the asymptotic analysis, we show how our results can be used for the mode identification and for the seismic studies of rapidly rotating stars. The conclusion is given in section 6.

The present work complements and extends a short recent paper (Lignières & Georgeot, 2008) by giving all the necessary details of the analysis and by presenting new results concerning (i) the ray dynamics at different rotation rates and for non-vanishing values of the angular momentum projection onto the rotation axis L_z , (ii) the analysis of extra regular patterns visible for some specific values of rotation, (iii) the number of modes in each frequency subset predicted by the asymptotic analysis, (iv) the visibility of the chaotic modes.

2. Formalism and numerical methods

In this section we present the equations governing the star model (subsection 2.1), the small perturbations about this model (subsection 2.2), the short-wavelength approximation of these per-

turbations (subsection 2.3) and the ray model for progressive acoustic waves (subsection 2.4). The numerical method used to compute the ray trajectories is described in subsection 2.5. The oscillation modes have been computed with the code described in Lignières et al. (2006) and Reese et al. (2006).

2.1. Polytopic model of rotating star

The model is a self-gravitating uniformly rotating monatomic gas ($\Gamma = 5/3$) verifying a polytopic relation assumed to give a reasonably good approximation of the relation between the pressure and the density in the star (Hansen, 1994):

$$P_0 = K\rho_0^{1+1/\mu} \quad (1)$$

$$0 = -\nabla P_0 - \rho_0 \nabla (\psi_0 - \Omega^2 w^2/2) \quad (2)$$

$$\Delta\psi_0 = 4\pi G\rho_0 \quad (3)$$

where P_0 is the pressure, ρ_0 the density, K the polytopic constant, μ the polytopic index, ψ_0 the gravitational potential, Ω the rotation rate, w the distance to the rotation axis and G the gravitational constant.

The uniform rotation ensures that the fluid is barotropic. A pseudo-enthalpy can then be introduced $h_0 = \int dP_0/\rho_0 = (1 + \mu)P_0/\rho_0$ and the integration of the hydrostatic equation reads:

$$h_0 = h_c - (\psi_0 - \psi_c) + \frac{1}{2}\Omega^2 w^2 \quad (4)$$

where the subscript “c” denotes the value in the center of the polytopic model. Equation (4) is then inserted into Poisson’s equation to yield:

$$\Delta\psi_0 = 4\pi G\rho_c \left(1 - \frac{\psi_0 - \psi_c}{h_c} + \frac{\Omega^2 w^2}{2h_c}\right)^\mu \quad (5)$$

Equation (5) is solved numerically, using an iterative scheme, as described in Rieutord et al. (2005).

Specifying the mass and the rotation rate of the star is not sufficient to determine the polytopic model in physical units. This requires to fix an additional parameter, for example the stellar radius (see Hansen (1994) for the non-rotating case and Christensen-Dalsgaard & Thompson (1999) for a brief discussion on a suitable parameter choice for rotating stars). In the following, however, we only present dimensionless quantities which do not depend on the choice of this additional parameter. The rotation rate Ω is compared to $\Omega_K = (GM/R_e^3)^{1/2}$ the limiting rotation rate for which the centrifugal acceleration equals the gravity at the equator, M being the stellar mass and R_e the equatorial radius. The star flatness is $\epsilon = 1 - R_p/R_e$ where R_p is the polar radius. The acoustic frequencies shall be expressed in terms of $\omega_0 = (GM/R_p^3)^{1/2}$, the inverse of a dynamical time scale, or ω_1 the lowest acoustic mode frequency of the stellar model considered.

2.2. Perturbation equations and boundary conditions

Time-harmonic small amplitude perturbations of the star model are studied under two basic assumptions. The first is to neglect the Coriolis force. This is a natural assumption to study high-frequency acoustic modes since the oscillation time scale is asymptotically much shorter than the Coriolis force time scale $1/(2\Omega)$. Moreover, complete calculations by Reese et al. (2006) (see figure 6 of this paper) have shown that Coriolis force effects

on the frequency are already very small for relatively low radial order (say $n \approx 5$). The second basic assumption is to neglect the viscosity and the non-adiabatic effects. This is a standard approximation in the asymptotic analysis since these effects have little influence on the value of the frequency. Both assumptions shall have important consequences on the acoustic ray dynamics described below. Neglecting the Coriolis force ensures that the dynamics is symmetric with respect to the time reversal while the absence of diffusion processes makes the dynamics conservative. Finally, the Cowling approximation valid for high frequencies enables to neglect the perturbation of the gravitational potential. Under these assumptions, the linear equations governing the evolution of small amplitude perturbations read:

$$\partial_t \rho + \nabla \cdot (\rho_0 \mathbf{u}) = 0, \quad (6)$$

$$\rho_0 \partial_t \mathbf{u} = -\nabla P + \rho \mathbf{g}_0, \quad (7)$$

$$\partial_t P + \mathbf{u} \cdot \nabla P_0 = c_s^2 (\partial_t \rho + \mathbf{u} \cdot \nabla \rho_0), \quad (8)$$

where \mathbf{u} , ρ and P , are respectively the Eulerian perturbations of velocity, density and pressure. The sound speed is $c_s = \sqrt{\Gamma P_0/\rho_0}$, Γ being the first adiabatic exponent of the gas, and $\mathbf{g}_0 = -\nabla (\psi_0 - \Omega^2 w^2/2)$ is the effective gravity.

As in Pekeris (1938), because the pressure and the temperature of the stellar model is zero at the surface, the only condition to impose on the perturbations is to be regular everywhere.

2.3. The short-wavelength approximation of the perturbation equations

The acoustic ray model results from a short-wavelength approximation of the perturbation equations (6), (7), (8), called the Wentzel-Kramers-Brillouin (WKB) approximation. Time-harmonic wave-like solutions of the form,

$$\Psi = \Re\{A(\mathbf{x}) \exp[i\Phi(\mathbf{x}) - i\omega t]\} = \Re\{\hat{\Psi}(\mathbf{x}) \exp(-i\omega t)\} \quad (9)$$

are sought under the assumption that their wavelength is much smaller than the typical lengthscale of the background medium. As discussed by Gough (1993), one expects a better approximation if the starting equations (6), (7), (8) are first reduced to a so-called normal form which avoids first order derivatives. This is done in Appendix A.1 leading to:

$$\frac{\omega_c^2 - \omega^2}{c_s^2} \hat{\Psi} + \frac{N_0^2}{\omega^2} \left[\Delta - \frac{1}{g_0^2} (\mathbf{g}_0 \cdot \nabla)(\mathbf{g}_0 \cdot \nabla) \right] \hat{\Psi} = \Delta \hat{\Psi} \quad (10)$$

where $\hat{\Psi} = \hat{P}/\alpha$, \hat{P} is the complex amplitude associated with the pressure perturbation $P = \Re\{\hat{P} \exp(-i\omega t)\}$ and α is a function of the background star model given by Eq. (A.8). The expressions of the cut-off frequency ω_c and the Brunt-Väisälä frequency N_0 are given respectively by (A.5) and (A.3). Note that the two left-hand-side terms of equation (10) account respectively for acoustic and gravity waves.

As detailed in Appendix A.2, the WKB approximation is then applied to (10). The dominant term of the expansion in powers of the ratio between the wavelength solution and the background typical lengthscale yields an equation governing the phase $\Phi(\mathbf{x})$, the so-called eikonal equation. The amplitude $A(\mathbf{x})$ is determined at the next order as a function of $\Phi(\mathbf{x})$. Neglecting the gravity waves by taking the high frequency limit, the eikonal equation reads:

$$\omega^2 = \omega_c^2 + c_s^2 k^2 \quad (11)$$

where $\mathbf{k} = \nabla\Phi$ is the wavevector. Moreover, for a polytropic model of star and using the approximation $\omega \gg N_0$ valid for high frequency acoustic modes, the function α is proportional to $\rho_0^{1/2}$ and the cut-off frequency ω_c is simplified to:

$$\omega_c^2 = \left[\frac{\Gamma\mu(\mu+2)}{2(\mu+1)} - 2 \right] \frac{g_0^2}{2h_0} + \frac{1}{2} \left(2 - \frac{\Gamma\mu}{\mu+1} \right) \nabla \cdot \mathbf{g}_0, \quad (12)$$

In the range of high frequency acoustic modes, the ω_c term is expected to be much smaller than ω in most parts of the star except near the surface where ω_c diverges. Note also that, despite the chosen notation, ω_c^2 can be negative near the center.

2.4. The acoustic ray model as a Hamiltonian system

The acoustic ray model consists in finding solutions of the eikonal equation (11) along some path called the ray path. This problem can be written in a Hamiltonian form where the solutions $(\mathbf{x}(t), \mathbf{k}(t))$ are conjugate variables of the Hamiltonian and t , the parameter along the path, is a time-like variable. To derive the Hamiltonian equations from the eikonal equation, one can apply a procedure valid for a general eikonal equation $D(\mathbf{k}, \omega, \mathbf{x}) = 0$ (e.g. Ott, 1993). This leads to the Hamiltonian $H' = \omega = \sqrt{c_s^2 \mathbf{k}^2 + \omega_c^2}$ (e.g. Lighthill, 1978). Another useful Hamiltonian formulation can be readily obtained by considering a path normal to the wavefront $\Phi(\mathbf{x}) = \text{const.}$ (this method being also used to determine optical rays in isotropic media of variable index (Born, 1999), the quantity $(\sqrt{1 - \omega_c^2/\omega^2})/c_s$ playing the role of the medium index $n(\mathbf{x})$). The ray path is thus defined by

$$\frac{d\mathbf{x}}{ds} = \frac{\mathbf{k}}{\|\mathbf{k}\|} = \frac{\nabla\Phi}{\|\nabla\Phi\|} \quad (13)$$

where s is the curvilinear coordinate along the ray. Differentiating (13) and using (11) then leads to the following system of ODEs:

$$\frac{d\mathbf{x}}{dt} = \tilde{\mathbf{k}} \quad (14)$$

$$\frac{d\tilde{\mathbf{k}}}{dt} = -\nabla W \quad (15)$$

$$W = -\frac{1}{2c_s^2} \left(1 - \frac{\omega_c^2}{\omega^2} \right) \quad (16)$$

where we use the frequency-scaled wavevector $\tilde{\mathbf{k}} = \mathbf{k}/\omega$ and the time-like variable t such that $dt = c_s ds / (1 - \omega_c^2/\omega^2)^{1/2}$.

As W only depends on the spatial variable \mathbf{x} , the second equation has the classical form of Newton's second law for the conservative force associated with the potential W (for a unit mass and a time variable t). This system can thus be written in a Hamiltonian form where

$$H = \frac{\tilde{\mathbf{k}}^2}{2} + W(\mathbf{x}) \quad (17)$$

is the Hamiltonian. According to the eikonal equation (11), H is equal to zero and the dynamics is therefore fully determined by the potential well W , where the frequency ω appears as a parameter. As $\omega \gg \omega_c$ away from the near surface layers, the potential increase towards the star center is given by the sound speed increase. Close to the surface, the potential barrier is due to the sharp increase of ω_c and provokes the wave back-reflection. While the location of the reflection surface depends on the frequency ω , we shall see that the dynamics is not strongly dependent on ω in the range of high-frequency acoustic modes here

considered. This can be expected since, as ω_c diverges towards the surface of the polytropic model of star, the location of $\omega = \omega_c$ does not vary rapidly with ω .

The potential being symmetric with respect to the rotation axis of the star, the angular momentum projection on this axis $\tilde{L}_z = r \sin \theta \tilde{k}_\phi$ is a constant of motion, where $\tilde{k}_\phi = \tilde{\mathbf{k}} \cdot \mathbf{e}_\phi$ and \mathbf{e}_ϕ is a unit vector in the azimuthal direction and $[r, \theta, \phi]$ are the spherical coordinates. Consequently, the projection of the ray trajectory on the meridional plane rotating with the ray at an angular velocity $d\phi/dt = \tilde{L}_z / (r \sin \theta)^2$ is governed by the two-degree-of-freedom Hamiltonian:

$$H_r = \frac{\tilde{\mathbf{k}}_p^2}{2} + W_r(\mathbf{x}) \quad (18)$$

where $\tilde{\mathbf{k}}_p = \tilde{\mathbf{k}} - \tilde{k}_\phi \mathbf{e}_\phi$ is the wavevector projected onto the rotating meridional plane and W_r is the effective potential of the reduced Hamiltonian H_r which now also depends on \tilde{L}_z as a parameter:

$$W_r(\mathbf{x}) = \frac{\tilde{L}_z^2}{2(r \sin \theta)^2} - \frac{1}{2c_s^2} \left(1 - \frac{\omega_c^2}{\omega^2} \right) \quad (19)$$

2.5. Numerical method for the ray dynamics

The acoustic ray dynamics has been investigated by integrating numerically Eqs. (14) and (15) using a 5th order Runge-Kutta method. The step size of the integration is chosen automatically to keep the local error estimate smaller than a given tolerance. To what extent this control of the local error ensures that the numerical solution is close to the true solution depends on the stability of the problem. For chaotic trajectories, the numerical error tends to grow rapidly while for stable trajectories this error remains of the same order as the relative error. The rapid growth of numerical errors is one of the characteristics of chaotic dynamics; however, this does not prevent to simulate such systems since for hyperbolic systems the shadowing theorem (Anosov, 1967; Sauer et al., 1997) ensures that an exact trajectory will remain close to the dynamics of each computed point for arbitrary times. Thus while a numerical trajectory diverges from the exact one, it nevertheless remains close to another exact trajectory, and therefore numerical errors do not prevent to obtain accurate phase space plots. We checked that the Poincaré surface of section shown in the next section are not significantly modified by decreasing the maximum allowed local error. We also checked the influence of the resolution of the background polytropic stellar model. Increasing this resolution from 62 to 92 Gauss-Lobatto points in the pseudo-radial direction has no significant effect on the Poincaré surface of section. Finally, the Hamiltonian conservation is used as an independent accuracy test on the computation.

3. Acoustic ray dynamics in rotating stars

In this section, we show that rotation strongly modifies the acoustic ray dynamics. Indeed, we find that, as rotation increases, the dynamics undergoes a transition from integrability (at zero rotation) to a mixed state where parts of the phase space display integrable behaviour while other parts are chaotic.

The nature of a dynamical system is best investigated by considering the structure of its phase space which contains both position and momentum coordinates. We thus first introduce the Poincaré Surface of Section (hereafter the PSS) which is a standard tool to visualize the phase space (subsection 3.1). Then we describe the phase space structure at zero rotation (subsection

3.2) and the main features of the generic phase space structure at high rotation rates (subsection 3.3). The detail of the transition to chaos as rotation increases is analyzed in subsection 3.4. As this last subsection makes use of several specific tools and theorems of dynamical systems theory, it might be skipped at first reading.

3.1. Phase space visualization : The Poincaré surface of section

As shown in subsection 2.4, acoustic rays with a given L_z are governed by a Hamiltonian with two degrees of freedom H_r . The associated phase space is therefore four-dimensional and difficult to visualize. A PSS is constructed by computing the intersection of the phase space trajectories with a chosen $(2N - 1)$ -dimensional surface, where N is the number of degrees of freedom of the system. If H is time-independent, then energy conservation implies that phase space trajectories stay on a $(2N - 1)$ -dimensional surface. The PSS is thus a $(2N - 2)$ -dimensional surface in general and a 2-dimensional surface in the present case.

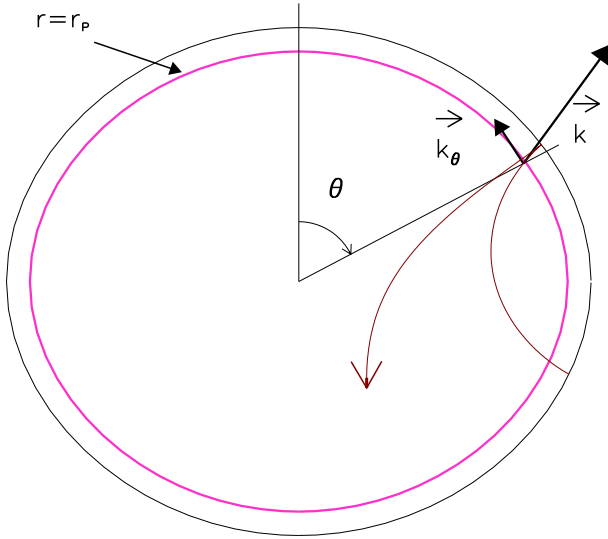


Fig. 1. (Color online) Intersection of an outgoing acoustic ray (red/arrow headed) with the $r = r_p(\theta)$ curve (magenta/thick). The point on the associated PSS is specified by the colatitude θ and the scaled latitudinal wavenumber component k_θ/ω at the intersection.

Different choices are possible for the PSS although some conditions are required to obtain a good description of the dynamics (see for example Ott, 1993). First, in order to provide a complete view of phase space, the PSS must be intersected by all phase space trajectories. Here we chose the curve $r_p(\theta) = r_s(\theta) - d$ situated at a fixed radial distance d from the stellar surface $r_s(\theta)$ displayed on Fig. 1. As shown in Appendix B.1 for the non-rotating case, the distance d can be chosen such that all relevant trajectories intersect this curve. The second condition is that, given a point on the PSS, the next point on the PSS has to be uniquely determined. This is ensured by counting the intersection with $r_p(\theta) = r_s(\theta) - d$ only when the trajectory comes

from on side of the $r = r_p(\theta)$ curve (here we consider the trajectories coming from the inner side). Finally, the coordinate system used to display the PSS is chosen in order that any surface of the PSS is conserved by the dynamics in the same way as four-dimensional volumes are preserved in phase space. The coordinates $[\theta, \tilde{k}_\theta]$ where \tilde{k}_θ is the latitudinal component of $\tilde{\mathbf{k}}$ in the natural basis $(\mathbf{E}^\zeta, \mathbf{E}^\theta, \mathbf{E}^\phi)$ associated with the coordinate system $[\zeta = r_s(\theta) - r, \theta, \phi]$ fulfill this condition (as shown in Appendix B.2).

PSS have been obtained by following many trajectories of different initial conditions. The number of trajectories together with the time during which they are computed determine the resolution by which the phase space is investigated. In principle, we should display PSS computed for different values of the frequency ω . However, as ω is varied in the range of frequency here considered, we found that the PSS remained practically unchanged. As discussed in subsection 2.4, this stems from the fact that the dynamics of the frequency-scaled wavevector \mathbf{k}/ω is weakly dependent on ω in this frequency range.

3.2. The non-rotating case $\Omega = 0$

The PSS at $\Omega = 0$ is described in this subsection. It will serve as a reference to investigate the evolution of the dynamics with rotation. Due to spherical symmetry, the norm of the angular momentum with respect to the star center

$$\tilde{L} = \sqrt{\tilde{k}_\theta^2 + \left(\frac{\tilde{L}_z}{\sin \theta}\right)^2} \quad (20)$$

is a conserved quantity. It follows that the intersection of any trajectory with the PSS belongs to a curve of the form:

$$\tilde{k}_\theta^2 = \tilde{L}^2 - \left(\frac{\tilde{L}_z}{\sin \theta}\right)^2 \quad (21)$$

For $\tilde{L}_z = 0$, these are the two straight lines $\tilde{k}_\theta = \pm \tilde{L}$ (see Fig. 3) while Eq. (21) yields a closed curve for $\tilde{L}_z \neq 0$ the trajectories being constrained to latitudes smaller than $\arcsin(|\tilde{L}_z|/\tilde{L})$ (see Fig. 5). This curve varies from a near rectangle to an ellipse as \tilde{L}_z grows from 0^+ to \tilde{L} .

The simplicity of the PSS reflects the fact that the system is integrable ((20) indeed provides the second invariant (in addition to H_r) of the reduced two-degree-of-freedom dynamical system). Every integrable system is structured in N -dimensional surfaces which are associated with specific values of the N constants of motion. This means that any trajectory is constrained to stay forever on one of these surfaces. They are called invariant tori because they are invariant through the dynamics and they have a torus-like topology. As we shall verify in the following, they play a crucial role in the transition to chaos as well as in the modes construction. The PSS at $\Omega = 0$ actually visualize the intersection of these tori with the $r = r_p$ surface.

Importantly, the invariant tori can be of two different types which determine their fate once the rotation is increased. Rational (or resonant) tori are such that all trajectories on the torus are periodic orbits (that is trajectories that close on themselves in phase space). In contrast, irrational tori are such that any trajectory densely covers the whole torus.

3.3. Phase space structure at high rotation rates

The main features of the phase space at high rotation rates are shown in Fig. 2 where the PSS at $\Omega = 0.59\Omega_K$ is displayed

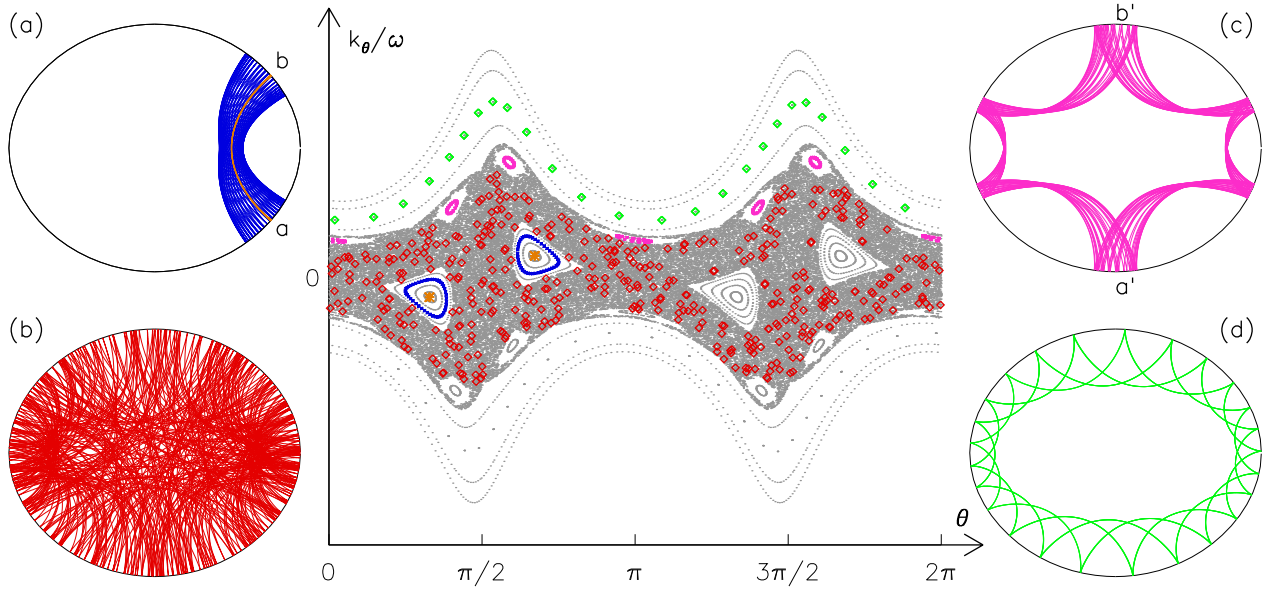


Fig. 2. (Color online) PSS at $\Omega = 0.59\Omega_K$ and typical acoustic rays associated with the four main phase space structures : (a) a 2-period island ray (blue/dark grey) and the associated periodic orbit with endpoints a and b (orange/light grey), (b) a chaotic ray (red/grey), (c) a 6-period island ray (magenta/light grey) and (d) a whispering gallery ray (green/light grey). On the PSS, (colored/grey) symbols (diamonds for the chaotic and whispering gallery rays, crosses for the 2-period and 6-period island rays) specify the po ints where these trajectories cross the PSS.

together with four acoustic rays shown on the position space as well as on the PSS. These rays belong to the three different types of phase space structures always present at high rotation rates. First, a large chaotic region appears (the grey region on Fig. 2). Chaotic rays, e.g. the red ray, are not constrained to stay on tori (that is on one-dimensional curves on the PSS) and thus fill up densely and ergodically a phase space volume (that is a surface on the PSS). Second, the island chain embedded in the large chaotic region is a common structure of phase space at high rotation rate. An important property of the island chain is to be structured by invariant tori centered on the periodic orbit of period 2 (the orange ray). The PSS also shows smaller island chains like the one formed around a 6-period periodic orbit (see the magenta ray). However, contrary to the 2-period island chain, such structures survive only up to a certain rotation rate. Third, the undulated curves present in the high \tilde{k}_θ region are formed by whispering gallery type trajectories (like the green ray), that is trajectories following the outer boundary. The associated tori correspond to the deformation of non-rotating tori which have not been destroyed yet at this rotation rate. Overall this type of phase space organization is typical of mixed systems with coexistence of chaotic regions and invariant tori (the structures encountered in integrable systems).

We note also that the main phase space structures are dynamically independent since no trajectory can cross from one region to the other. We will show in section 4 that the very existence of these structures enables to organize the spectrum into independent frequency subsets. In the following subsection, the generic character of these structures is checked by computing the PSS at different rotation.

3.4. Transition to chaos $\Omega \neq 0$

The evolution of the dynamics with increased rotation is first described for $\tilde{L}_z = 0$ and then for $\tilde{L}_z \neq 0$.

3.4.1. The $\tilde{L}_z = 0$ case

The PSS computed at the three rotation rates $\Omega/\Omega_K = [0, 0.15, 0.32]$ respectively corresponding to the three flatness $\epsilon = [0, 0.01, 0.05]$ are displayed in Fig. 3 to illustrate the effect of a small centrifugal deformation on the ray dynamics. This perturbation of the integrable $\Omega = 0$ system is very similar to one described by the KAM-theorem (Chirikov, 1979; Giannoni et al., 1991; Ott, 1993; Gutzwiller, 1990; Lichtenberg & Lieberman, 1992; Lazutkin, 1993). Indeed, for a smooth small perturbation of an integrable Hamiltonian, this theorem states that the tori of the integrable system which survived the perturbation occupy most of the phase space volume. More specifically most of the irrational tori while being continuously perturbed can still be associated with N invariants, thus keeping their torus structure. This is the case of the undulated lines observed in the high \tilde{k}_θ domain of Fig. 3. By contrast, all rational tori are immediately destroyed for a non-vanishing perturbation. The KAM theorem implies that, despite the fact that the destroyed rational tori form a dense set in the phase space, the volume they occupy vanishes as the perturbation goes to zero.

The theory of KAM-type transition to chaos also describes how resonant tori disappear. In our case, they correspond to one-dimensional curves on the PSS, formed by families of periodic orbits. All orbits of the same torus will have the same period q . The so-called Poincaré-Birkhoff theorem predicts that a (smooth) small perturbation will transform this one-dimensional curve into a chain of q stable points belonging to the same periodic orbit and surrounded by stable islands, intertwined with q unstable periodic points. A small chaotic zone appears in the vicinity of the unstable fixed points and grows with the perturbation. The stable islands have themselves an intricate self-similar structure of small island chains surrounded by invariant structure (tori). This phenomenon is illustrated at $\Omega/\Omega_K = 0.15$ in Fig. 3 where, near the $\tilde{k}_\theta = 0$ curve, we can observe the 2-period is-

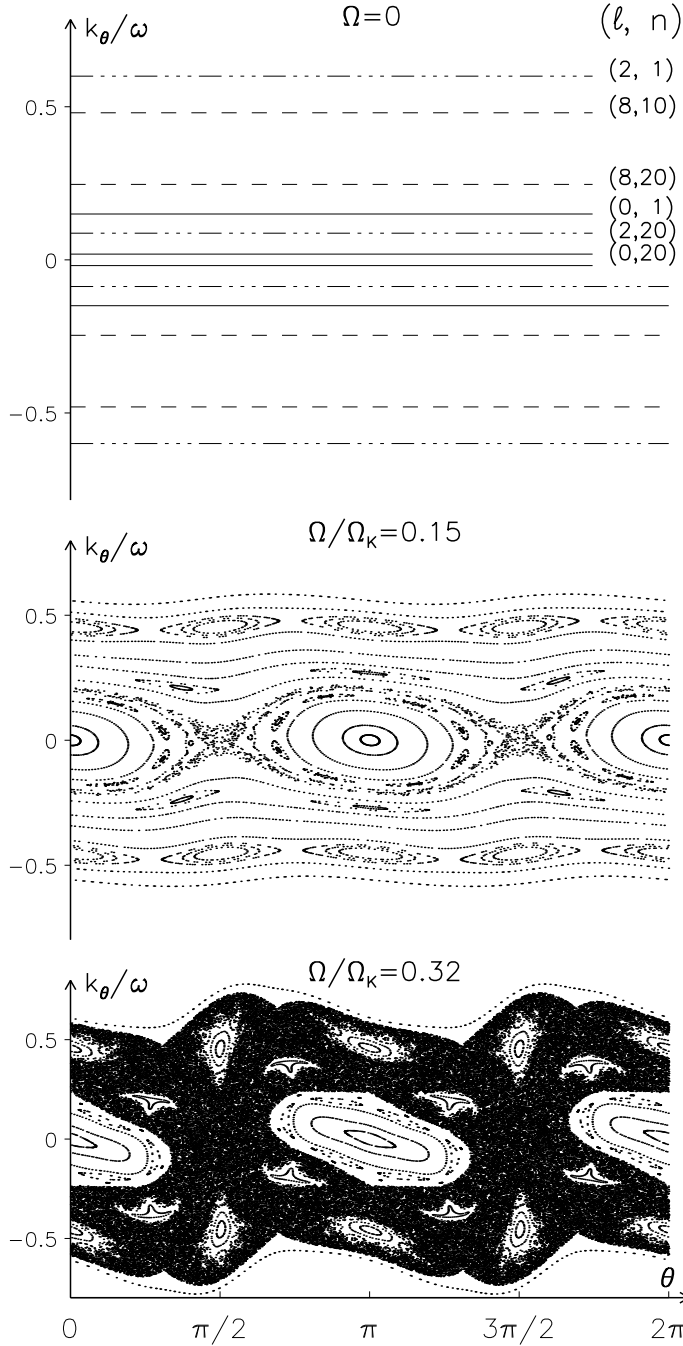


Fig. 3. Three $\tilde{L}_z = 0$ PSS at small rotation rates showing the transition to chaos. The unit of k_θ/ω is ω_0^{-1} . Island chains and chaotic regions appear around respectively stable and unstable periodic orbits. On the $\Omega = 0$ PSS, the straight lines correspond to intersections with mode-carrying-tori specified by the degree and radial order of the mode.

land chain around the $q = 2$ stable periodic points and the small chaotic region around the corresponding unstable points. This results from the destabilization of the resonant torus associated with the periodic orbits along the diameters of the spherical star. Note that the width of the island chains (resonance width) is expected to be approximately proportional to the square root of the perturbation, and decreases with q .

What occurs for large perturbations following the KAM-type transition of integrable Hamiltonians has been studied in many

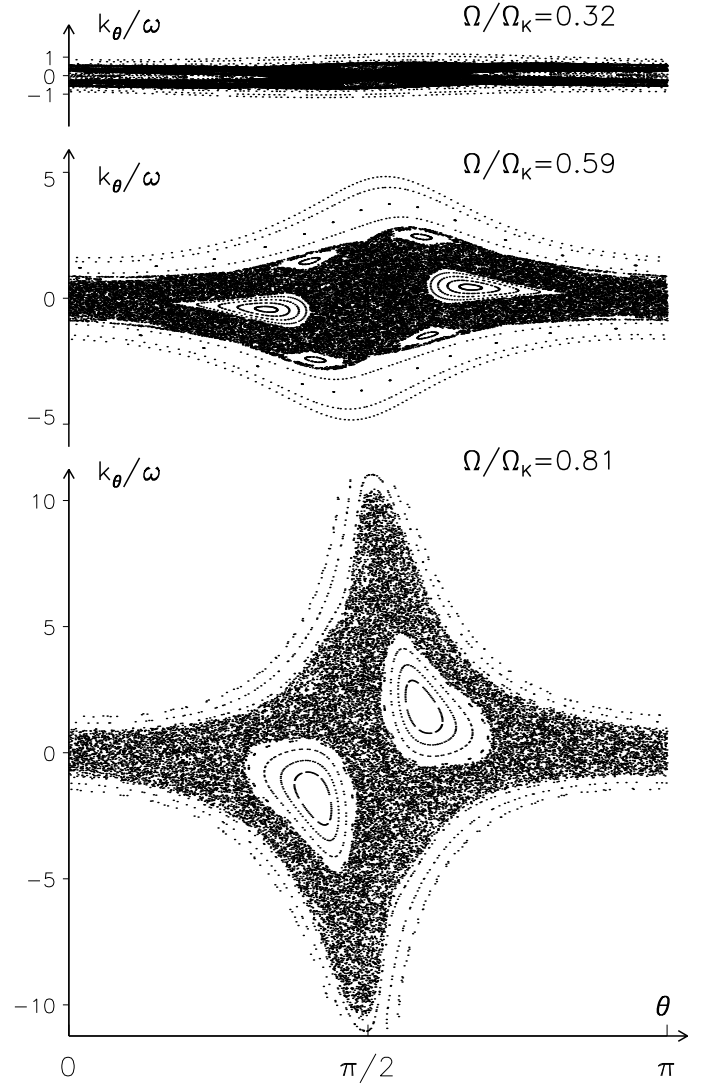


Fig. 4. Three $\tilde{L}_z = 0$ PSS visualizing the evolution of phase space as a function of rotation. All these PSS show the 2-period periodic orbit island chain embedded in a central chaotic region. As rotation increases, the 2-period island chain moves towards the equator while the central chaotic region enlarges. Note that the first $\Omega = 0.32\Omega_K$ PSS is displayed with a different scale in Fig. 3. The units are the same as in Fig. 3.

systems. The general phenomenology which emerges also corresponds to what we observe in our system for increased rotation (see the PSS of Fig. 4 computed for $\Omega/\Omega_K = [0.32, 0.59, 0.81]$ corresponding to the flatness $\epsilon = [0.05, 0.15, 0.25]$). The surviving irrational tori as well as the island chains are progressively destroyed. This leads to the enlargement of the chaotic regions which were originally confined by these tori. This is illustrated in Figs. 3 and 4 where the surface of the central chaotic region becomes progressively larger with rotation. The island chains typically undergo a series of bifurcations for increasing perturbation; the most common bifurcation is the period-doubling one, where a stable periodic orbit of period q is changed to an unstable orbit plus a stable orbit of period $2q$. As the sequence of bifurcations goes on, stable orbits are of longer and longer period until they eventually disappear. The destruction of stable regions is visible between $\Omega = 0.59\Omega_K$ and $\Omega = 0.81\Omega_K$ (Fig. 4), as the

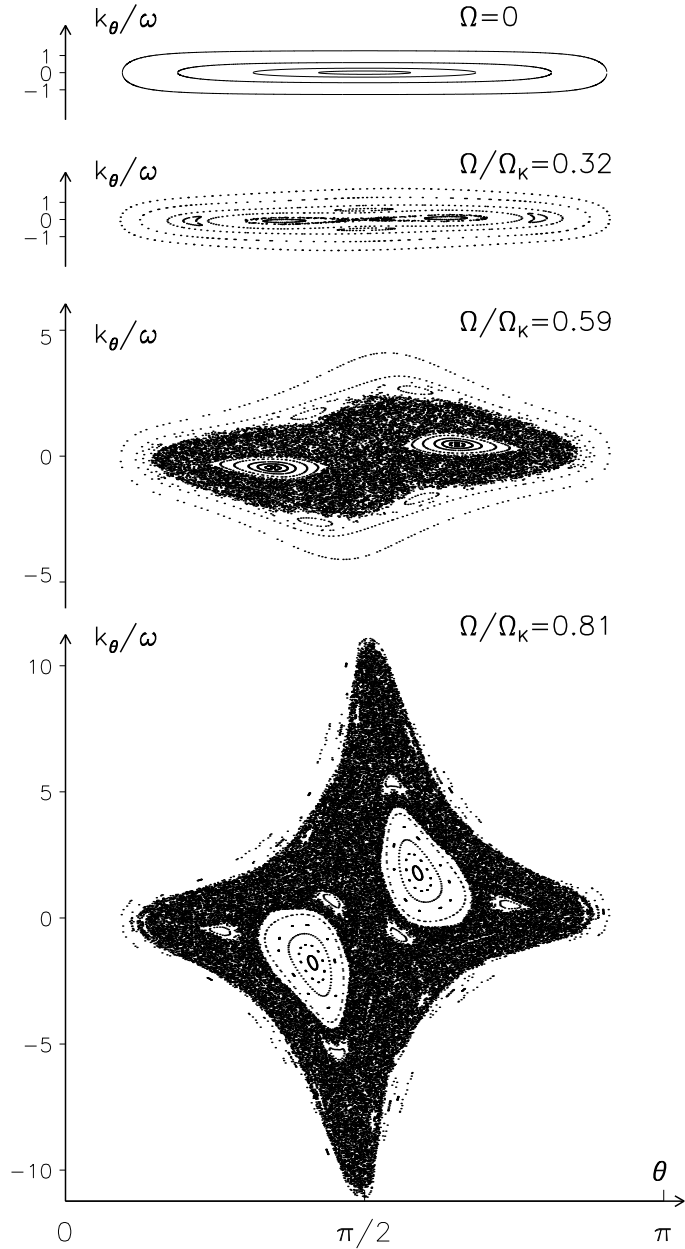


Fig. 5. Three $\tilde{L}_z = 0.4/\omega_0$ PSS visualizing the evolution of phase space as a function of rotation. The evolution is qualitatively similar to the $\tilde{L}_z = 0$ case although the enlargement of the central chaotic region occurs at higher rotation rates. Same units as in Fig. 3.

6-period island chain embedded in the chaotic central region at $\Omega = 0.59\Omega_K$ has disappeared at higher rotation. As mentioned above, the fact that the largest stable island originates from a short periodic orbit (here a 2-period periodic orbit) is also a common feature of the KAM-type transitions to chaos.

While not visible on this figure, a zoom on other regions of the PSS would show the same process going on at small scales. It is however clear that the irrational tori associated with large values of \tilde{L} survive longer, this property being also encountered in classical billiards (Lazutkin, 1993), where tori close to the billiard boundary are the most robust.

3.4.2. The $\tilde{L}_z \neq 0$ case

Qualitatively, the transition to chaos is very similar to the $\tilde{L}_z = 0$ case. This is shown in Fig. 5 where PSS computed for $\tilde{L}_z = 0.4/\omega_0$, are shown for increased rotation. The main effect of increasing \tilde{L}_z is to delay the transition towards chaos to higher rotation rates. Indeed by comparing PSS computed at the same rotation rate (see Fig. 4 and Fig. 5), one observes that the central chaotic region is more constrained by surviving tori for larger \tilde{L}_z values. For example at $\Omega = 0.32\Omega_K$ the central chaotic region is much more developed for $\tilde{L}_z = 0$ than for $\tilde{L}_z = 0.4/\omega_0$. The $\Omega = 0.59\Omega_K$ PSS provides another example since for $\tilde{L}_z = 0.4/\omega_0$ the island chain associated with the 6-period orbit is separated by a surviving KAM tori from the central chaotic region while such a stable structure has already been destroyed for $\tilde{L}_z = 0$. Finally, at $\Omega = 0.81\Omega_K$, we can observe that the central chaotic region for $\tilde{L}_z = 0.4/\omega_0$ contains visible surviving structures while this is not the case for $\tilde{L}_z = 0$.

The slower transition to chaos can be interpreted as being due to the angular constraint $-\arcsin(|\tilde{L}_z|/\tilde{L}) < \theta < \arcsin(|\tilde{L}_z|/\tilde{L})$ imposed on the dynamics. This is compatible with the fact that for infinite \tilde{L}_z the trajectories are confined to the equatorial plane and the dynamics becomes integrable because of the circular symmetry of this asymptotic limit.

4. The asymptotic properties of the acoustic modes

In this section, we show that ray dynamics provides a qualitative and quantitative understanding of the high-frequency acoustic modes.

The question to be addressed is that of how to construct modes, that is standing waves, from the short-wavelength propagating waves described by ray dynamics. Such modes construction is expected to be approximately valid in the asymptotic regime of high-frequencies (this asymptotic regime is called the semi-classical regime in a quantum physics context). As mentioned in the introduction, the answer depends on the nature of the Hamiltonian system. For integrable systems, each phase space trajectory remains on an invariant torus and this enables to construct modes from a positively interfering superposition of these travelling waves on the torus. This is not any more the case for chaotic systems, where the ray dynamics provides no invariant structures on which to build modes.

Thus for integrable systems, the modes and the frequencies can in principle be explicitly determined from the acoustic rays through well-known formulas called Einstein-Brillouin-Keller (EBK) quantization after the name of its main contributors. We shall recall the results obtained by Gough (1993) when applying the EBK method to spherical stars (sub-section 4.1). While this procedure is not applicable to chaotic systems, other concepts and methods have been developed and tested in quantum physics to interpret the non-integrable dynamics. These concepts have been also applied to other wave phenomena such as those observed in e.g. microwave resonators (Stöckmann & Stein, 1990), lasing cavities (Nöckel & Stone, 1997), quartz blocks (Ellegaard et al., 1996) and underwater waves (Brown et al., 2003). Their potential interest for helioseismology has been suggested, although not demonstrated, by Perdang (1988) and Kosovichev & Perdang (1988). Here, we shall apply them to the non-integrable ray dynamics of rapidly rotating stars. More specifically, we have seen in section 3 that the ray dynamics of such stars corresponds to a mixed system where parts of phase space display integrable behaviour and other parts chaotic dynamics. In such case, the organiza-

tion/classification of modes in the semi-classical regime is expected to closely follow the structure of phase space. Near-integrable regions of phase space like the island chains are amenable to EBK quantization, leading to a regular frequency spectrum, while the modes originating from chaotic regions have an irregular frequency spectrum with generic statistical properties. Another important information provided by ray dynamics is the averaged number of modes that can be constructed from a given phase space region, this number being proportional to the volume of the region considered.

In the following, we explicit these concepts and methods in the context of stellar acoustics (sub-sections 4.1, 4.2, 4.3). Then, their relevance to describe the asymptotic properties of the acoustic modes is tested by confronting their predictions to the actual properties of high-frequency acoustic modes (sub-sections 4.4, 4.5, 4.6, 4.7). These modes are axisymmetric modes in the frequency range $[9\omega_1, 12\omega_1]$, ω_1 being the lowest acoustic mode frequency of the stellar model considered. They have been computed for a $\Omega = 0.59\Omega_K$ uniformly rotating $\mu = 3$ polytropic model of star and under the same assumptions as for ray dynamics (adiabatic perturbations, no Coriolis acceleration, Cowling approximation).

4.1. The integrable case $\Omega = 0$

To build modes from the ray dynamics, the wave-like solution $\hat{\Psi} = A(\mathbf{x}) \exp[i\Phi(\mathbf{x})]$ is regarded as a function of the phase space variables $\mathbf{x}, \mathbf{k} = \nabla\Phi$ that is subsequently projected onto the position space. The condition that $\exp[i\Phi(\mathbf{x})]$ be single-valued on the position space requires that for any phase space trajectory that closes on itself in the position space, the variation of Φ along this closed contour is a multiple of 2π . As trajectories of an integrable system stay on invariant tori, this condition leads to the EBK formula:

$$\int_{C_j} \mathbf{k} \cdot d\mathbf{x} = 2\pi(n_j + \frac{\beta_j}{4}) \quad (22)$$

where C_j is any closed contour on a given torus and n_j and β_j are non-negative integers. The integer β_j called the Maslov index is introduced to account for a $\pi/2$ phase lag that must added each time the contour crosses a caustic. Indeed, the caustic corresponds to the boundary of the torus projection onto position space; the amplitude A taken in the position space is discontinuous there, leading to the $\pi/2$ phase loss (see Keller & Rubinow (1960) for details).

While this expression is valid for any closed contour on the torus, it can be shown that it gives the same condition for all contours that can be continuously deformed to the same one. Thus in fact the EBK quantization yields N independent conditions, as only N topologically independent closed paths exist on a N -dimensional torus. As these closed paths do not need to be actual trajectories of the dynamical system, the usual way to construct EBK solutions is to choose contours for which the formulas are simple to compute. The quantization conditions thus select a particular torus on which a mode can be built, irrespective of the fact that the torus is resonant or non-resonant. For spherical stars, three independent contours on a torus specified by L, L_z and ω can be obtained by varying one of the spherical coordinates and fixing the other two. Using similar contours, Gough (1993) obtained the three conditions:

$$\int_{r_i}^{r_e} \left(\frac{\omega^2 - \omega_c^2}{c_s^2} - \frac{L^2}{r^2} \right)^{1/2} dr = (n - \frac{1}{2})\pi, \quad L = \ell + \frac{1}{2}, \quad L_z = m \quad (23)$$

where n, ℓ, m are non negative integer, r_i and r_e being the internal and external caustic respectively. Note that $L = \omega\tilde{L}$ and $L_z = \omega\tilde{L}_z$. The associated eigenmodes have been also explicitly constructed from the trajectories on the selected torus. As shown by Gough (1993), the result of this EBK quantization is practically identical to the usual asymptotic theory of acoustic modes in spherical stars which uses the separability of the three-dimensional eigenvalue problem and a WKB approximation of the resulting 1-D boundary value problem in the radial direction (in the usual analysis, $L = \sqrt{\ell(\ell+1)}$, differs from the EBK result, especially at low ℓ values). This shows that the integers n, ℓ, m derived from the EBK quantization conditions do correspond to the order, degree and the azimuthal number of the acoustic modes in spherical stars.

The tori on which the eigenmodes are constructed can be visualized on the PSS. For example, the $(\ell, n, m) = (8, 10, 0)$ mode is associated with the torus $\tilde{L} = \pm(\ell + 1/2)/\omega_{n,\ell,m}$, $\tilde{L}_z = 0$ which imprint on the PSS are the straight lines $\tilde{k}_\theta = \pm\tilde{L}$. The intersection of various mode-carrying tori with the $\tilde{L}_z = 0$ PSS are shown in Fig. 3. High radial order modes approach the central $\tilde{k}_\theta = 0$ line while large degree modes occupy the high \tilde{k}_θ region.

4.2. Chaotic systems

It has been widely recognized in the past decades that most dynamical systems are not integrable and therefore display various degrees of chaos. The quantum chaos field has studied quantum systems whose short-wavelength classical limit displays such chaotic behavior. As has been recognized early by Einstein (1917) the EBK quantization explained in the above paragraph cannot be applied to such systems. Indeed, no N -dimensional invariant structure exists on which to apply conditions of constructive interference like the EBK condition. Rather, the semi-classical limit of these chaotic systems yields a Fourier-like formula which connects the set of all classical periodic orbits to the whole spectrum. This formula, called Gutzwiller trace formula (Gutzwiller, 1990) is much more delicate to use than EBK formulas, since it represents a divergent sum from which information can be extracted only through refined mathematical and numerical methods.

On the other hand, the very complexity of chaotic systems leads to statistical universalities. Indeed, in a similar way as statistical physics emerges from the random behavior of individual particles, in chaotic systems the randomness induced by chaos leads to robust statistical properties of eigenmodes. Contrary to modes of integrable systems, which are localized on individual tori selected by the EBK conditions, in chaotic systems modes are generally not associated to a specific structure in phase space, and are ergodic on the energy surface. It has been found that one can model such systems by replacing the Hamiltonian by a matrix whose entries are random variables with Gaussian distributions. Such ensembles of *Random Matrices*, which contain no free parameter but take into account the symmetries of the system, can give precise predictions, which have been found to describe accurately many statistical properties of the modes of systems with a chaotic classical limit. This has been conjectured and checked numerically for many systems (Bohigas et al., 1984; Giannoni et al., 1991).

The comparison with Random Matrix predictions is often done through the statistical analysis of the frequency spectrum. In general the density of modes as a function of the frequency

$$d(\omega) = \sum_n \delta(\omega - \omega_n) \quad (24)$$

where δ is the delta function, can be written as the sum of two functions

$$d(\omega) = d^{\text{av}}(\omega) + d^{\text{fluct}}(\omega). \quad (25)$$

The quantity $d^{\text{av}}(\omega)$ (hereafter called the Weyl term) is a smooth function which describes the average density of modes at a given frequency. It has been known from the beginning of the twentieth century that this term can be calculated from general geometric features of the system such as phase space volume and therefore is independent of the chaotic or integrable nature of the dynamics ($d^{\text{av}}(\omega)$ is estimated for stellar acoustic modes in subsection 4.7). In contrast, the function d^{fluct} which describes the fluctuations around the mean position of eigenfrequencies strongly depends on the nature of the dynamics. (Note that most textbooks on this subject use the quantum physics terminology, that is 'energy level' instead of frequency and 'density of states' instead of density of modes).

The spectra of integrable systems are predicted to be uncorrelated, and in general this leads to fluctuations given by the Poisson distribution (Berry & Tabor, 1977). In contrast, for chaotic systems these fluctuations should be given by Random Matrix Theory. The theory of Random Matrices has therefore been developed in order to compute analytically the predictions for specific quantities, which in turn could be compared to numerical data for real systems. A popular quantity to describe fluctuations in spectra is the *spacing distribution* $P(\delta)$, which is the distribution of spacings in frequency between consecutive eigenfrequencies, once the frequency differences have been rescaled by the Weyl term such that the average spacing is one. The function $P(\delta)$ measures the correlations at short distances in frequency in the spectrum, and therefore does not give information about all statistical properties, but is nevertheless very useful since the predictions are strikingly different for the Poisson distribution and for Random Matrix Theory. While the Poisson distribution corresponds to $P(\delta) = \exp(-\delta)$, the prediction of Random Matrix Theory is the Wigner distribution $P(\delta) = \pi\delta/2 \exp(-\pi\delta^2/4)$, which displays frequency repulsion (level repulsion in the quantum terminology) at short distances (small δ) and falls off faster than Poisson at large δ .

4.3. Mixed systems

We have seen in section 3 that the acoustic ray dynamics in rotating stars has a mixed character as chaotic regions coexist with stables structures like island chains or invariant tori. Such mixed system are actually the most common in nature, completely integrable and chaotic systems being limiting cases.

In the context of quantum chaos, seminal studies of these systems by Percival (1973) and Berry & Robnik (1984) enabled to conjecture that a good description of their spectrum at high energy is obtained by quantizing independently the structured and chaotic parts. While a zoom on island regions would reveal a complex structure involving chaotic trajectories and chains of smaller islands, these small scale details can be neglected for the island quantization if the mode wavelength remains large as compared to these scales. Instead, the presence of a large number of invariant structures constrains enough the dynamics to make the system similar to a purely integrable structure to which EBK quantization applies. These region are then called near-integrable.

Thus subsets of modes can be associated to the different near-integrable island chains, while other subsets correspond to the chaotic zones. In each subset, the modes behave as if they

were constructed from an isolated system. Thus in mixed systems the frequency spectrum can be described as a superposition of independent frequency subsets associated with the different phase space regions. Subsequent works have shown this picture to be a good approximation of actual spectra, although in some cases certain correlations are present between the frequency subsets due to the presence of partial barriers in phase space or to the existence of modes localized at the border between zones (Bohigas et al., 1993).

The acoustic ray dynamics of rapidly rotating stars being of this mixed type, one can expect such an organization of the spectrum to be valid, even though the modes are of quite large wavelength compared to previous studies in quantum chaos. To test this hypothesis, it is convenient to compute a phase-space representation of the modes. Indeed, the chaotic or near-integrable zones are well-defined in phase space while their projections in position space, were modes are usually pictured, are generally much more difficult to separate.

4.4. Associating modes to rays

Constructing phase space representations for modes has been envisioned since the beginning of quantum mechanics, since it enables to test the quantum-classical correspondence accurately. Contrary to states of a classical system which are defined by a point in phase space, modes have always a finite extension in phase space since they have a finite wavelength and their localization in wavenumber space is, according to Fourier analysis, inversely proportional to their localization in physical space. Any mode occupies a finite volume of the order of $(2\pi)^N$ in the physical/wavenumber phase space (a $(2\pi/\omega)^N$ volume in the physical/scaled-wavenumber $(\mathbf{x}, \tilde{\mathbf{k}})$ phase space or a $(2\pi\hbar)^N$ volume in the position/momentum phase space of quantum physics). Wigner (1932) was the first to construct a phase space function representing a mode, but this so-called Wigner function has the disadvantage of being positive or negative, and therefore cannot be interpreted as a probability distribution of the mode. To circumvent this problem, one way is to smooth the Wigner function by a Gaussian convolution. The resulting function, called Husimi distribution function (Chang & Shi, 1986), is always real and nonnegative and can be understood equivalently as the projection of the mode onto a Gaussian wave packet centered around \mathbf{x} and $\tilde{\mathbf{k}}$:

$$\mathcal{H}(\mathbf{x}, \tilde{\mathbf{k}}) = \left| \int \Psi(\mathbf{x}') \exp(-\|\mathbf{x}' - \mathbf{x}\|^2/(2\Delta_x^2)) \exp(i\omega\tilde{\mathbf{k}} \cdot \mathbf{x}') d\mathbf{x}' \right|^2 \quad (26)$$

where $\Psi(\mathbf{x}')$ is the mode and $\exp(-\|\mathbf{x}' - \mathbf{x}\|^2/(2\Delta_x^2)) \exp(i\omega\tilde{\mathbf{k}} \cdot \mathbf{x}')$ the Gaussian wavepacket. In this expression, the width of the wavepacket Δ_x determines the resolution of the Husimi function in the spatial direction, the resolution in the scaled-wavenumber $\Delta_{\tilde{\mathbf{k}}}$ being such that $\Delta_x \Delta_{\tilde{\mathbf{k}}} \approx 1/\omega$. These quantities determine the minimal extent of the mode representation in both directions.

The computed modes are 3D modes and they shall be compared with the reduced ray dynamics computed on a 2D meridional plane. As shown in the spherical case by Gough (1993), the amplitude of a 3D axisymmetric mode constructed from acoustic rays obtained on neighboring meridional planes decreases as $(r \sin \theta)^{(-1/2)}$ because away from the rotation axis the distance between the planes and thus the density of rays increases. Thus, the computed 3D modes have been scaled by $(r \sin \theta)^{(1/2)}$ to better represent the mode amplitude on a meridional plane. Moreover to obtain a phase-space representation limited to the

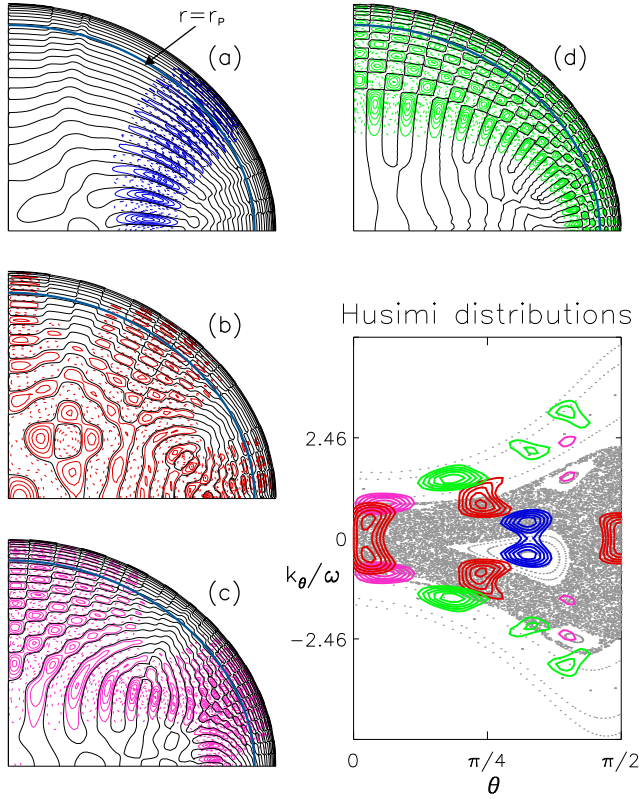


Fig. 6. (Color online) Four axisymmetric modes and their phase space representation : (a) a 2-period island mode (blue/dark grey), (b) a chaotic mode (red/grey), (c) a 6-period island mode (magenta/light grey) and (d) a whispering gallery mode (green/light grey). The amplitude distribution of the scaled mode Ψ' is represented by its nodal lines (black) and its positive (full colored/grey lines) and negative (dashed colored/grey lines) level curves. The Husimi distributions of the four modes computed for the same $\Delta_s = 0.12R_e$ are represented by their level curves.

PSS, we actually computed the Husimi's distribution function of the 1D cut of the mode taken along the PSS:

$$\mathcal{H}(s, \tilde{k}) = \left| \int \Psi'(s') \exp(-(s' - s)^2 / (2\Delta_s^2)) \exp(i\omega \tilde{k} s') ds' \right|^2 \quad (27)$$

where Ψ' is the scaled version of the mode $\hat{\Psi} = \hat{P}/\alpha$ solution of Eqs. (6), (7) and (8), s is a curvilinear coordinate along the curve $r = r_p$ and $\tilde{k} = \tilde{\mathbf{k}} \cdot \mathbf{e}_p$ is the scaled-wavenumber in the direction tangent to this curve, \mathbf{e}_p being a unit vector tangent to the curve. \mathcal{H} is then expressed in terms of the PSS coordinates using the following relations between $[\theta, \tilde{k}_\theta]$ and $[s, \tilde{k}]$:

$$s = \int_{\theta_0}^{\theta} \left(r_p^2 + \left(\frac{dr_p}{d\theta} \right)^2 \right)^{1/2} d\theta' \quad \tilde{k} = \tilde{k}_\theta \mathbf{E}^\theta \cdot \mathbf{e}_p \quad (28)$$

The vector \mathbf{E}^θ is defined in appendix B.2. The integral (27) is performed in the interval $[\theta - \pi, \theta + \pi]$, the mode being prolonged by symmetry outside the $[0, \pi]$ interval.

The Husimi function has been computed for the axisymmetric modes of the $\Omega = 0.59\Omega_K$ star and its contour plot is compared with the PSS of the ray dynamics computed for the same star model. Fig. 6 illustrates this process by showing the

position space as well as the phase space representation of four typical modes. As can be observed, the modes can be clearly associated with one of the main structure of the phase space namely, the 2-period island chain, the large central chaotic region, the 6-period island chain or the whispering gallery region. On the PSS, we note however that the Husimi function is symmetric with respect to \tilde{k}_θ while the dynamics is not. This difference is due to the fact that the PSS is constructed only with $\tilde{k}_r > 0$ intersecting trajectories while the Husimi function computed from the mode cut on the $r = r_p$ contains no information about the sign of \tilde{k}_r . Nevertheless, in the high-frequency interval $[9\omega_1, 12\omega_1]$ that we studied in detail, any ambiguity on the phase space location can always be resolved using the additional information on the mode distribution in the position space. In this frequency interval, we thus classified the modes according to their localization in phase space distinguishing the 2-period island modes, the chaotic modes, the 6-period island modes and the whispering gallery modes associated with the corresponding phase space regions. As a result, the full frequency spectrum can be decomposed into sub-spectra associated with phase space structures. Fig. 7 displays the four sub-spectra.

In the following, we shall analyze these sub-spectra and test whether the Percival and Berry-Robnik conjecture described in subsection 4.3 applies to acoustic modes in rapidly rotating stars. We first study the regular character of the sub-spectra issued from near-integrable phase space regions (sub-section 4.5) and then consider the spectrum of chaotic modes (sub-section 4.6).

4.5. The regular spectra

A spectrum is said to be regular if it can be described by a function of N integers, N being the degree of freedom of the system. In accordance with previous studies by Lignières et al. (2006), Lignières & Georgeot (2008) and Reese et al. (2008), the spectrum of the 2-period island modes is well-fitted by the empirical formula

$$\omega_{n\ell} = n\delta_n + \ell\delta_\ell + \alpha \quad (29)$$

confirming the regular nature of this spectrum that is also clearly apparent on Fig. 7(a).

The 6-period island mode spectrum shown in Fig. 7(c) is also regular as it is closely fitted by the even simpler formula:

$$\omega_{n'} = n'\delta_{n'} + \alpha' \quad (30)$$

Indeed, the root mean square error between this empirical fit and the actual spectrum is equal to 1.9 percent of δ'_n (where δ'_n has been determined as the mean of the spacing between consecutive frequencies and α' is fixed such that the model is exact at a reference frequency).

While a simple linear law such as Eqs. (29) or (30) does not apply to the whispering gallery modes, there are strong evidences that this sub-spectrum is also regular. Thanks to the regularity of the nodal lines pattern (as apparent in Fig. 6(d)), two integers corresponding to the number of nodes along the polar axis and to the number of nodes following the internal caustic can be easily attributed to each modes. When plotted against the number of caustic nodes (as in Fig. 7(d)), the spectrum clearly shows a regular behavior. The fact that the function of these two integers describing the spectrum is however not as simple as Eqs. (29) or (30) is expected from what we know about the regular spectrum of high degree modes in spherical stars (see for example Christensen-Dalsgaard (1980)).

The regularity of the three sub-spectra issued from near-integrable phase space regions is fully in accordance with the Percival's conjecture. An important consequence is that theoretical model of these spectra can in principle be obtained from the EBK quantization of the invariant structures of the corresponding near-integrable regions. As a result we should be able to relate the potentially observable quantities δ_n , δ_ℓ or δ'_n to the star properties. In practice, the standard method is first to construct the normal forms around the central periodic orbit in order to describe the dynamics in the island, and then use the EBK quantization scheme to find the asymptotic formula for the modes (Bohigas et al., 1993; Lazutkin, 1993). While such a program is outside the scope of the present paper, we mention below the result obtained in Lignières & Georgeot (2008) for the 2-period island modes using an equivalent procedure, which may be more physically transparent, and extend it to the 6-period island modes.

As already noted, the propagation of acoustic waves in our system is similar to the propagation of light in an inhomogeneous medium, the role of the medium index being played by $1/c_s$. The construction of standing wave solutions between two bounding surfaces has been investigated intensively in the context of the study of laser modes in cavities (Kogelnik & Li, 1966) and it consists in applying the paraxial approximation in the vicinity of the optical axis. While generally applied to homogeneous media, this approximation can be extended to the non-homogeneous case as in Permittin & Smirnov (1996). Applying this formalism to the acoustic modes associated with periodic orbits, Lignières & Georgeot (2008) found a model spectrum equivalent to Eq. (29) with

$$\delta_n = \frac{\pi}{\int_a^b d\sigma/c_s} \quad \text{and} \quad \delta_\ell = 2 \frac{\int_a^b c_s d\sigma/w^2}{\int_a^b d\sigma/c_s} \quad (31)$$

where σ is the curvilinear coordinate along the periodic orbit and the integral is computed between the end points of the orbit (these points are shown in Fig. 2 for the 2-period and the 6-period periodic orbits being denoted (a,b) and (a',b') respectively). The quantity $w(\sigma)$ in the expression of δ_ℓ describes the spreading of the wave beam in the direction transverse to the periodic orbit and verifies a differential equation which depends on the sound speed and its transverse derivative taken along the periodic orbit. Moreover the integers n and ℓ correspond respectively to the number of nodes in the directions parallel and transverse to the orbit (see Lignières & Georgeot (2008) for details).

When applied to the 2-period periodic orbit, this theoretical expression of δ_n yields a value $0.5635\omega_0$ which differs from its empirical value by only 2.2 percent.

The 6-period island mode spectrum can be modeled in the same way. In the frequency interval considered, these modes have a similar structure in the direction transverse to the central orbit and should therefore be associated with the same ℓ value. The model spectrum has thus the same form as Eq (30) where

$$\delta'_n = \frac{\pi}{\int_{a'}^{b'} d\sigma/c_s} \quad (32)$$

As for the 2-period modes, we find that this theoretical value of δ'_n differs by only a few percents from the empirical determination of $\delta'_n = 0.186\omega_0$.

These two examples show that ray dynamics can provide a quite accurate model of the near-integrable spectra in the relatively low frequency regime considered. Moreover the model

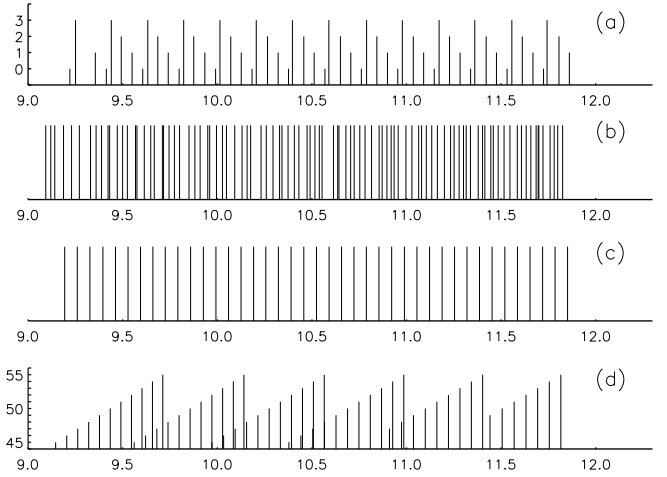


Fig. 7. Frequency sub-spectra of four classes of axisymmetric modes : (a) the 2-period island modes, (b) the chaotic modes antisymmetric with respect to the equator, (c) the 6-period island modes and (d) some whispering gallery modes. For the sub-spectra (a) and (d), the height of the vertical bar specifies one of the two quantum numbers characterizing the mode.

(29) of the 2-period island mode spectrum remains reasonably accurate at lower frequencies (Lignières et al., 2006) and can be extended to non-axisymmetric modes (Reese et al., 2008).

4.6. The chaotic modes

A large subset of the frequencies correspond to modes localized in the chaotic zone of phase space (the chaotic modes). As we have seen in subsection 4.2, one should not expect regular patterns for this part of the spectrum. Rather, the chaotic character of the phase space should be reflected in specific statistical properties of the sub-spectrum, which should follow predictions from Random Matrix Theory. To test this predictions, we have studied the distribution of the consecutive frequency spacings $\delta_i = \omega_{i+1} - \omega_i$ of the chaotic modes. Fig. 8 shows the integrated distribution $N(\Delta) = \int_0^\Delta P(\delta) d\delta$ (with spacings normalized by the mean level spacing within the chaotic subset, as should be done). The distribution is constructed from the two independent distributions obtained for the equatorially symmetric and anti-symmetric modes, corresponding to around 187 modes in total. Although the difficulty to solve Eqs. (6), (7), (8) prevents us to reach as large frequency samples as can be obtained for other systems (Bohigas et al., 1984), the numerically computed $N(\Delta)$ agrees well with the Random Matrix predictions, and is clearly different from the Poisson distribution typical of integrable systems. This result indicates that these modes, selected by means of the comparison between their localization in phase space and the ray dynamics, have indeed the frequency statistics expected for chaotic modes. We therefore think that this confirms the validity of the ray model, and gives a strong evidence that wave chaos actually occurs in rapidly rotating stars.

We note that the modes we identify as chaotic are located in the chaotic zone but cover only part of it, as for the example of Fig. 6. We think this is partly due to the relatively low frequency considered, which prevents ergodicity of the modes to be clearly visible. In addition, it is known that certain low-energy eigenfunctions of chaotic systems called scars are concentrated along short periodic orbits of the system (Heller, 1984). In this case,

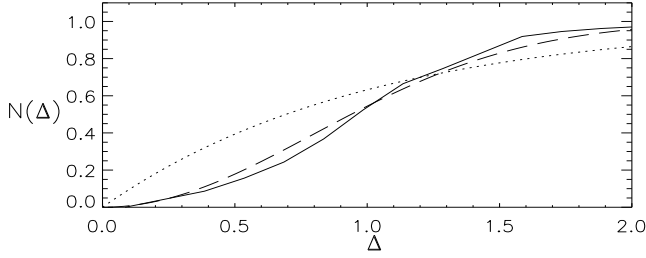


Fig. 8. Integrated spacing distribution $N(\Delta)$ of the chaotic modes (full line). The dashed line shows $N(\Delta)$ for the Gaussian Orthogonal Ensemble of Random Matrix Theory while the dotted line shows the integrated Poisson distribution typical of integrable systems.

rather than being ergodic, some individual modes are effectively localized in the vicinity of such orbits. This effect can create some subsequences of low-energy modes with regular frequency patterns, even if the distribution of frequency spacings follows the predictions of Random Matrix Theory. Precise investigation of this phenomenon in the context of stellar acoustic modes may be important.

4.7. Predicting the number of modes in each sub-spectrum : The Weyl formula

In this subsection, we show that ray dynamics enables to estimate the number of chaotic and island modes present within a given frequency interval. This information is complementary to the regular/irregular properties of the associated sub-spectra shown in the previous section and it is crucial to build an asymptotic model of the frequency spectrum.

We have seen in subsection 4.2 that the density of modes as a function of the frequency $d(\omega)$ can be written as the sum of a smooth part $d^{av}(\omega)$ and an oscillatory part $d^{fluct}(\omega)$ (see Eq. (25)). Weyl, at the beginning of the twentieth century, derived analytically an asymptotic expansion of $d^{av}(\omega)$ (Weyl, 1912). The leading term of the Weyl formula can be obtained from general principles. We have seen (subsection 4.4) that in average a mode occupies a $(2\pi)^N$ volume in the physical/wavenumber phase space. The averaged number of modes in a given phase space volume can thus be estimated as the volume of phase space available divided by $(2\pi)^N$, the volume occupied by one mode. In the following, we shall first verify that the leading term of the Weyl formula yields a reasonable estimate of the number of modes in the case of spherically symmetric stars. Then, we shall calculate the phase space volume of the chaotic and island regions and confront the result with those obtained from the numerical computation of modes at $\Omega = 0.59\Omega_K$.

The Hamiltonian formulation $H' = \omega = \sqrt{c_s^2 k^2 + \omega_c^2}$ is best suited for this calculation. The averaged number of modes below a given frequency ω reads:

$$\bar{N}(\omega) = \frac{1}{(2\pi)^N} \mathcal{V}(\omega) \quad (33)$$

where $\mathcal{V}(\omega)$ is the phase space volume corresponding to energies smaller than ω defined as

$$\mathcal{V}(\omega) = \int_{\mathcal{A}(\omega)} d\mathbf{k}^N d\mathbf{x}^N \quad (34)$$

where $\mathcal{A}(\omega)$ is the phase space region defined as $H'(\mathbf{x}, \mathbf{k}) \leq \omega$.

For spherical stars, the dynamics can be reduced to the one-degree-of-freedom dynamics characterized by the reduced Hamiltonian $H^{sph} = \sqrt{c_s(r)^2(k_r^2 + L^2/r^2) + \omega_c^2}$. Applying the above formula to H^{sph} , the double integral $\mathcal{V}(\omega)$ can be integrated over k_r to give:

$$\bar{N}^{sph}(\omega) = \frac{1}{\pi} \int_{r_i}^{r_e} \sqrt{\frac{\omega^2 - \omega_c^2}{c_s^2} - \frac{L^2}{r^2}} dr \quad (35)$$

which is thus the estimated number of modes of given L and L_z with a frequency smaller than ω . This estimation can be compared to the results of the usual asymptotic theory (see Eq. (23)). Accordingly, $\bar{N}^{sph}(\omega) = n - 1/2$, where n is the radial order associated to the frequency ω but is also the number of modes below the frequency ω for fixed values of L and L_z . We therefore conclude that in the 1D-spherical case the first term of Weyl's formula yields a reasonable approximation of the averaged mode density.

In rotating stars, to estimate $\bar{N}(\omega)$ the number of modes below ω for a given L_z , we use the two-degree-of-freedom Hamiltonian $H'_r = \omega = \sqrt{c_s^2(k_p^2 + L_z^2/(r \sin \theta)^2) + \omega_c^2}$, and integrate the 4-dimensional volume integral in the wavenumber directions to obtain:

$$\bar{N}(\omega) = \frac{1}{4\pi} \iint_{S_m} \frac{\omega^2 - \omega_c^2}{c_s^2} - \frac{L_z^2}{(r \sin \theta)^2} dS_m \quad (36)$$

where S_m is the portion of the meridional plane surface where the integrand is positive. While providing the total number of modes, this expression does not give the fraction of chaotic, island or whispering gallery modes which are important quantities to model the spectrum. These quantities can nevertheless be obtained by computing the corresponding phase space volumes and by applying Eq. (33). This has been done for $\Omega/\Omega_K = 0.59$ since at this rotation rate we can compare the results of Weyl's formula to the numbers of chaotic and island modes obtained from the direct mode computation and the classification through the Husimi distribution.

The 4-dimensional phase space volumes have been evaluated using a Monte-Carlo quadrature method: points are randomly chosen in a known volume V_M that includes the volume V to be computed. The proportion of points inside V approximates the ratio V/V_M , thus providing an approximate value of V . To decide whether a given point is inside or outside V , we used space filling trajectories on the torus delimiting the volume V . Two phase space volumes have been computed at $\Omega/\Omega_K = 0.59$. The first one includes the large chaotic region as well as the island chains around the 2-period and 6-period orbits. The second volume corresponds to the 2-period island chain. The details of the calculation and an estimation of the error on the volume determination are given in Appendix C.

As a result, the leading term of the Weyl formula yields 34 ± 2 modes in the 2-period island chain and 270 ± 8 modes outside the whispering gallery region in the frequency interval $[9.42\omega_1, 11.85\omega_1]$. This value has to be compared with the 50 island modes and the 276 modes outside the whispering gallery region obtained using the Husimi phase space representation of the modes computed in the same frequency interval.

The difference between the estimation given by (33) and the actual number of modes in each subset of the frequency spectrum corresponds most likely to the next order in the asymptotic expansion of the density of modes. Indeed, Eq. (33) is only the first term in an asymptotic expansion, the next term being usually proportional to the length of the boundary between phase

space zones. At relatively low frequency, this term can be significant. Another source of imprecision can stem from the fact that at such relatively low frequency some partial barriers in phase space can trap island-like modes in the vicinity of the island, enlarging the effective size of the regular zone. Indeed, for some of the modes classified as island modes, the Husimi distribution is not entirely inside the island, the outer part remaining close to the island. Nevertheless, our study shows that Eq. (33) gives a reliable estimate of the relative sizes of the frequency subsets which can be obtained without any knowledge of the spectrum itself.

5. Discussion and applications to asteroseismology

In this section we discuss the validity of the assumptions of our asymptotic analysis, and the implications of our results for the asteroseismology of rapidly rotating stars.

5.1. Assumptions of the asymptotic analysis

The WKB assumption underlying the asymptotic analysis is not justified for the lowest frequency acoustic modes. While determining the limit of validity of the different results presented here is outside the scope of the paper, we know that the regularities of the 2-period island mode sub-spectrum are relevant down to about the 5th radial order acoustic pulsations (see Lignières et al. (2006) and Reese et al. (2008) for details).

Another important precaution when applying the present analysis stems from the fact that the interpretation of the ray dynamics depends on the frequency range considered. Indeed, if extremely high frequency modes were to exist, their properties would closely follow the phase space structure up to its smallest details. This means for example that such modes could be associated with the very small chaotic regions which exist inside the island chains or in between the surviving KAM tori of the whispering gallery regions. On the other hand, finite-wavelength effects have to be taken into account when interpreting the ray dynamics at finite frequencies. For example, the regularities of the island mode spectra in the $[9\omega_1, 12\omega_1]$ interval show that the small chaotic zones within the island chain can be overlooked in this frequency range. The same reasoning holds if one wants to interpret the ray dynamics at small rotation rates (see Fig. 3). The tiny chaotic regions predicted by the KAM theorem could be interpreted as a proof for the existence of a chaotic mode frequency subset at vanishingly small rotation. However, these modes should have such a short wavelength to "fit in" the chaotic region that they may simply not exist (because they are strongly dissipated by diffusive effects or their frequency is so high that they are not reflected at the surface).

Ray dynamics can not account directly for the coupling effects between two modes associated with two dynamically isolated regions of phase space (as occurs for example in the well known tunneling effect). Indeed, while trajectories can not cross the dynamical barrier between the chaotic and the island chain regions, an island mode can be present on either side of the barrier if its frequency is very close to the one of a chaotic mode (and vice versa). As usual for mode avoided crossings, the mode distribution can thus be significantly perturbed by the coupling but the frequency is only slightly affected especially in the high-frequency regime. Quantifying the effects of such avoided crossings would require a specific study.

The WKB assumption that the wavelength is much shorter than the typical background lengthscale breaks down for low-

frequency acoustic mode but also when the typical lengthscale of the stellar model becomes very small. This can occur in real stars, especially at the upper limit of the core convective zone where strong composition gradients built in during evolution. The effect of such a discontinuity has been studied for spherical stars (Vorontsov, 1988; Gough, 1990; Ballot et al., 2004) and has been found to add an oscillatory component to Tassoul's asymptotic formula, but not to remove the asymptotic structure altogether. To treat properly the discontinuities in non-spherical stars, the ray dynamics approach has to be extended by taking into account the splitting of rays at the discontinuity, corresponding to the reflected and transmitted waves. Once this is incorporated in the formalism, quantum chaos techniques can be applied as was done for billiards in Blumel et al. (1996a) and the Weyl formula can also be computed (Prange et al., 1996).

Apart from the treatment of eventual sound-speed discontinuities, the asymptotic analysis presented in this paper for uniformly rotating polytropic stellar models can be readily applied to realistic stellar models. The details of the dynamics will change as they depend on the sound speed distribution of the model considered. However, we do not expect that the mixed character of the dynamics and thus the irregular/regular nature of the spectrum will change. This has to be confirmed by specific ray dynamics studies. In particular, the effects of the advection by a differentially rotating flow should be investigated.

Lifting the two assumptions concerning the adiabaticity of the perturbations and the Coriolis force omission should not significantly modify the results of the asymptotic analysis. Non-adiabatic calculations are known to have a small effect on the frequency values while the legitimate omission of the Coriolis force for high frequency motions is already relevant for quite low frequency as shown in Reese et al. (2006).

5.2. Implications for mode identification

The asymptotic analysis provides qualitative and quantitative informations which can be used to identify high frequency acoustic modes in an observed spectrum. First the basic structure of the spectrum can be readily deduced from the ray dynamics phase space structure visualized by the PSS. Indeed, we have seen that the $\Omega = 0.59\Omega_K$ PSS correctly predicts that the spectrum of axis-symmetric modes is a superposition of four frequency subsets, three regular and one irregular. If we now look at the $\Omega = 0.81\Omega_K$ PSS, we see that the spectrum structure should be similar except that the regular sub-spectrum associated with the 6-period island chain is no longer present since this island chain has disappeared at this rotation rate. In the same way, at $\Omega = 0.15\Omega_K$, we expect a simple superposition of a whispering gallery sub-spectrum and a 2-period island mode sub-spectrum since the chaotic regions are not sufficiently developed at this rotation rate. Such informations, while only qualitative, are crucial to guide the identification process. Moreover this information is obtained at a relatively low computing cost since the PSS calculation is much-less demanding than the numerical computation of modes and frequencies.

Then, the EBK quantization of the near-integrable regions provides the values of the uniform frequency spacings (as given by Eq. (29)) that should be present in the observed spectrum. When analyzing an observed spectrum, the star model is not known, thus only estimates of these uniform spacings can be obtained. However, these estimates enable to focus the search for regularities on a smaller range of values.

Finally as we also know the frequency statistics of chaotic modes and the number of modes in each sub-spectrum (through

Weyl's formula) the asymptotic analysis enables to construct asymptotic spectra. The chaotic mode frequencies can be obtained as a realization of the Wigner distribution although, in this case, their frequencies could not be individually identified with observed ones. Nevertheless, such a synthetic spectrum should be very useful to test identification methods, especially the search for the regularities hidden in the complete spectrum (see below).

Among the additional informations which can help constraint the mode identification are the mode visibility and the mode excitation. The excitation mechanism have been studied so far in the spherically symmetric case and need to be reconsidered for rapidly rotating stars. The mode visibility also deserves a specific study notably the calculation of the intensity variations induced by the oscillation in a gravity darkened atmosphere. However, the visibility strongly depends on the cancellation effects on the disk-integrated light. Here, we can estimate this effect by integrating the surface Lagrangian temperature perturbation of the axisymmetric modes computed for the $\Omega = 0.59\Omega_K$ rotating polytropic star. The disk-averaging factor is defined as:

$$D(i) = \frac{1}{\pi R_e^2 \delta T_0} \iint_{S_v} \delta T(\theta, \phi) d\mathbf{S} \cdot \mathbf{e}_i \quad (37)$$

where i is the inclination angle between the line-of-sight and the rotation axis, \mathbf{e}_i is a unit vector in the observer's direction, δT is the spatial part of the Lagrangian temperature perturbation at the stellar surface and S_v is the visible part of the stellar surface. The mode amplitude is normalized by δT_0 the root mean square of the perturbation over the whole stellar surface

$$\delta T_0 = \left(\frac{\iint_S \delta T^2(\theta, \phi) dS}{S} \right)^{1/2} \quad (38)$$

and the projected visible surface is normalized by πR_e^2 , the visible disk surface for a star seen pole-on. With these normalizations the disk-averaging factor of an hypothetical mode uniformly distributed on the surface and seen pole-on is unity. The method of the calculation is detailed in Appendix D and corrects the calculation described in Appendix C of Lignières et al. (2006) which actually only provides an approximate value of $D(i)$.

Figure 9 shows the spectrum of axisymmetric modes whose disk-averaging factor exceeds 2.5 percent. It appears that the disk-averaging effect does not allow to discard as many modes as for spherical stars. Indeed, in a given frequency interval and for the same visibility threshold, we find that the number of visible modes is more than three time higher in the $\Omega = 0.59\Omega_K$ star than in a spherical star. Among the four classes of modes, the 2-period island modes and the chaotic modes have similar visibilities and are significantly more visible than the 6-period island modes and whispering gallery modes. In Fig. 9, a few 6-period island modes are visible while no whispering gallery modes exceed the chosen threshold.

The relatively high visibility of the chaotic modes with respect to the 2-period island modes was not expected as the typical horizontal wavelength of the chaotic modes is generally significantly shorter than the one of the 2-period island modes (see Fig. 6). We think that this is due to the irregular nature of the node pattern of the chaotic modes which makes the cancellation effect less effective than for regularly spaced nodes (like the whispering gallery modes). A practical consequence of this property is that, at such a rotation rate, methods to disentangle the regular spectrum from the irregular one should be developed.

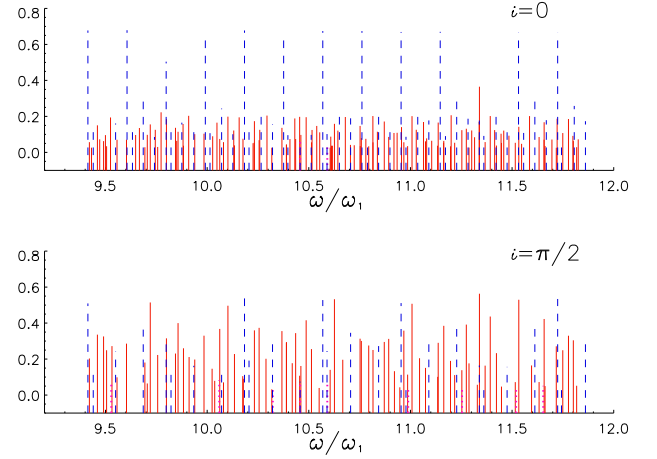


Fig. 9. (Color online) Frequency spectra of axisymmetric modes where the amplitude is given by the normalized disk-averaging factor $D(i)$ for a star seen pole-on $i = 0$ and equator-on $i = \pi/2$. Only frequencies such that $D(i) \geq 2.5\%$ are displayed and antisymmetric modes fully cancel out equator-on. The 2-period island modes (blue/dashed lines) and the chaotic modes (red/continuous lines) are the most visible while only a few 6-period island modes (magenta/dotted lines) and no whispering gallery mode exceed the 2.5% level.

5.3. Seismic constraints

Constraints on the star can be obtained once the island and chaotic modes sub-spectra are separated. Through the quantization formulas of the regular modes, the asymptotic analysis provides the relation between regular frequency spacings and the physical properties of the star. For example, according to Eq. (31), the seismic observable δ_n depends on the value of the sound velocity along the path of the 2-period periodic orbit. The quantity δ_ℓ depends in addition on the second order transverse derivative of the sound velocity along the same path and the radius of curvature of the bounding surfaces. The 2-period periodic orbit remains along the polar axis up to relatively high rotation rates (see Fig. 3 at $\Omega/\Omega_K = [0.15, 0.32]$). This implies that all the modes trapped within the corresponding island chain probe the center of the star which is known to be crucial for stellar evolution theory. It would be worth investigating if high order and low degree modes of rapidly rotating solar-type pulsators are in this case. Other informations on the star can be deduced from the numbers of island modes or chaotic modes. Indeed the number of mode in each class is related to the volume of the corresponding phase space regions (see subsection 4.7) which in turns depends on the stellar model.

Further constraints on the star are expected from the identification of the chaotic modes. Contrary to the regular modes built on invariant torus, the modes built on chaotic region are not localized in phase space and are expected to be ergodic within their region of propagation. This property turns out to be of particular interest for asteroseismology. The chaotic modes of the main chaotic region are indeed distributed all over the position space and do not avoid the stellar core like all the non-radial modes in non-rotating stars. Thus, in rapidly rotating stars, the chaotic p-modes have the potential to probe the physics of the core. While the sensitivity of the chaotic modes to this physics needs to be tested, quantum chaos studies indicate that the spatial distribu-

tion of chaotic modes is highly sensitive to changes in the models (Schack & Caves, 1993; Benenti et al., 2002).

6. Conclusion

We have constructed the ray dynamics in uniformly rotating polytropic stars and have presented the tools and concepts that enable to interpret it in terms of modes properties. Accordingly, the acoustic frequency spectrum of rapidly rotating polytropic stars is a superposition of frequency subsets associated with dynamically independent phase space regions. The spectra associated with near-integrable regions are regular while those associated with chaotic regions are irregular but with specific statistical properties. Besides this global qualitative understanding of the spectrum organization, the ray dynamics also provides quantitative information. The EBK quantization of the near-integrable regions enables to explicitly construct the modes and the spectrum from the ray dynamics. For the chaotic modes, the analysis of subsection 4.6 shows that there exists a parameter-free model of their frequency statistics. Moreover, we have seen in subsection 4.7 that we can estimate from the ray dynamics the number of modes in each frequency subset. These results have been confronted with the properties of acoustic modes computed in the frequency interval $[9\omega_1, 12\omega_1]$ showing that the present asymptotic analysis does provide a quite accurate qualitative and quantitative understanding of the actual spectrum in this frequency range.

The analysis of section 5 argues for the importance of this asymptotic analysis for the mode identification and for the asteroseismology of rapidly rotating stars. Indeed, the asymptotic results and the estimation of the mode visibilities tells us that the separation of the frequencies between chaotic and regular modes is a necessary prerequisite in order to analyze the spectrum. When this is done, the observed regular spacings like δ_n and δ_ℓ can be related to the internal property of the star thanks to the asymptotic analysis.

Further work on this theory could help the analysis of the observed spectra. First, it is important to establish more precise formulas such as Eq. (31) for the regular modes corresponding to the different stability islands. The structure of chaotic modes at low frequency should be studied in more details, in frequency ranges lower than the ones used in the present work. This will allow to test the asymptotic analysis in frequency ranges where it is not supposed to hold in principle, but which are part of the observed spectra. Encouragingly, the regularity of the 2-period island modes has been already demonstrated in a relatively low radial order range $5 \leq n \leq 10$ (Lignières et al., 2006; Reese et al., 2008), and more generally, in quantum mechanics the semi-classical analysis has been found to apply in energy ranges much lower than expected. Such a study would also allow to probe if the presence of scars (see section 4.6), which should be seen only at low frequencies, can organize part of the chaotic sub-spectrum. These studies will in particular enable to produce theoretical synthetic spectra which embody all the semi-classical information and can be used to test methods of analysis before dealing with actual spectra.

Outside the scope of the asymptotic analysis *per se*, the mode identification would greatly benefit of accurate visibility computations, of modes excitation studies and obviously of more realistic models of centrifugally distorted rapidly rotating stars (Roxburgh, 2006; MacGregor et al., 2007; Espinosa Lara & Rieutord, 2007).

In conclusion, we believe that the asymptotic analysis we exposed is a promising way to interpret the spectrum of rapidly ro-

tating stars. We have demonstrated that it can describe numerical spectra, and think that with suitable refinements it should provide an important tool for the analysis of observed spectra such as those obtained by the instruments COROT and KEPLER.

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Appendix A: The WKB approximation of the stellar oscillation equations (6), (7), (8)

The equations are first written in a normal form, then the eikonal equation is obtained using the WKB approximation.

A.1. Normal form

We first eliminate the perturbation velocity \mathbf{u} from the equations (6), (7), (8) governing the evolution of the perturbations. Using equations (7), the time derivative of Eqs. (6) and (8) reads:

$$\partial_{tt}^2 \rho + \nabla \cdot (\rho \mathbf{g}_0) = \Delta P, \quad (\text{A.1})$$

$$c_s^2 (\partial_{tt}^2 + N_0^2) \rho = \partial_{tt}^2 P + \frac{c_s^2 N_0^2}{g_0^2} \mathbf{g}_0 \cdot \nabla P \quad (\text{A.2})$$

where N_0 is the Brunt-Väisälä frequency defined as

$$N_0^2 = \mathbf{g}_0 \cdot \left(\frac{\nabla \rho_0}{\rho_0} - \frac{1}{\Gamma} \frac{\nabla P_0}{P_0} \right) \quad (\text{A.3})$$

Seeking harmonic solutions in time, the variable are written $F = \hat{F} \exp(i\omega t)$. Then, using Eq. (A.2), \hat{P} is expressed in terms of \hat{P} and replaced in Eq. (A.1) to yield:

$$\begin{aligned} & \left[-\omega^4 + \omega^2 c_s^2 f \nabla \cdot \left(\frac{\mathbf{g}_0}{c_s^2 f} \right) \right] \hat{P} + \\ & \left[\omega^2 \left(1 + \frac{c_s^2 N_0^2}{g_0^2} \right) - c_s^2 f \nabla \cdot \left(\frac{N_0^2 \mathbf{g}_0}{g_0^2 f} \right) \right] \mathbf{g}_0 \cdot \nabla \hat{P} - \\ & \frac{c_s^2 N_0^2}{g_0^2} \mathbf{g}_0 \cdot \nabla (\mathbf{g}_0 \cdot \nabla \hat{P}) - \omega^2 c_s^2 f \Delta \hat{P} = 0 \end{aligned} \quad (\text{A.4})$$

We then look for a function α such that the substitution $\hat{P} = \alpha \hat{\Psi}$ eliminates the first derivative term. The result is given by Eq. (10) where :

$$\omega_c^2 = \frac{g_0^2 B^2}{4c_s^2} + c_s^2 f \nabla \cdot \left(\frac{\mathbf{g}_0}{c_s^2 f} \right) - \frac{c_s^2}{2} \nabla \cdot \left(\frac{B \mathbf{g}_0}{c_s^2} \right) + \frac{(1-f)}{2} B g_0^2 \nabla \cdot \left(\frac{\mathbf{g}_0}{g_0^2} \right) \quad (\text{A.5})$$

where

$$B = 1 + \frac{c_s^2 N_0^2}{g_0^2} - c_s^2 \nabla \cdot \left(\frac{(1-f) \mathbf{g}_0}{f g_0^2} \right) \quad (\text{A.6})$$

$$f = 1 - \frac{N_0^2}{\omega^2} \quad (\text{A.7})$$

The α function is given by:

$$\nabla \alpha = \frac{B}{2c_s^2} \alpha \mathbf{g}_0 \quad (\text{A.8})$$

The expression of ω_c can be simplified in the limit $\omega \gg N_0$ to give:

$$\omega_c^2 = \frac{g_0^2}{4c_s^2} \left(1 + \frac{c_s^2 N_0^2}{g_0^2} \right)^2 + \frac{c_s^2}{2} \nabla \cdot \left(\left(1 - \frac{c_s^2 N_0^2}{g_0^2} \right) \frac{\mathbf{g}_0}{c_s^2} \right) \quad (\text{A.9})$$

For polytropes $P_0 = K \varrho_0^{1+1/\mu}$, the quantities describing the equilibrium model can be expressed in terms of the enthalpy h_0 as follows:

$$\begin{aligned} \mathbf{g}_0 &= \nabla h_0 & c_s^2 &= \frac{\Gamma}{\mu+1} h_0 \\ N_0^2 &= \left(\frac{\mu \Gamma}{\mu+1} - 1 \right) \frac{g_0^2}{c_s^2} \end{aligned} \quad (\text{A.10})$$

Equation (A.9) can then be simplified to give Eq. (12). We note that while the $\omega \gg N_0$ is expected to be valid for acoustic modes in real stars, the fact that the Brunt-Väisälä frequency becomes infinite at the surface of a polytropic model implies that this approximation is not valid close to the surface of such models.

A.2. Eikonal equation

We look for wave-like solutions (9) of the normal form of the perturbation equation (10) under the assumption that $1/\Lambda$ the ratio between the wavelength of the solution and the background typical lengthscale is very small. Accordingly, the solution is expanded as:

$$\Phi = \Lambda (\Phi_0 + \frac{1}{\Lambda} \Phi_1 \dots) \quad A = A_0 + \frac{1}{\Lambda} A_1 \dots \quad (\text{A.11})$$

and the eikonal equation corresponds to the leading order of the expanded solution.

The highest $O(\Lambda^2)$ terms verify:

$$\frac{\omega^2 - \omega_c^2}{c_s^2} + \frac{N_0^2}{\omega^2} \Lambda^2 (\nabla \Phi_0)_\perp^2 = \Lambda^2 (\nabla \Phi_0)^2 \quad (\text{A.12})$$

where the $(\nabla \Phi_0)_\perp = \nabla \Phi_0 - (\nabla \Phi_0 \cdot \mathbf{n}_0) \mathbf{n}_0$, \mathbf{n}_0 being the outward unit vector in the direction opposite to the effective gravity. The effective eikonal equation then depends on the ordering of ω/ω_0 with respect to Λ . If $\omega/\omega_0 = O(\Lambda)$, then the above equation simplifies to:

$$\frac{\omega^2 - \omega_c^2}{c_s^2} = (\nabla \Phi_0)^2 \quad (\text{A.13})$$

which corresponds to the dispersion relation of acoustic waves. The ω_c term is retained because its sharp increase near the surface provokes the back reflection of the acoustic wave.

On the other hand, if $\omega/\omega_0 = O(1)$, then we obtain

$$-\frac{\omega_c^2}{c_s^2} + \frac{N_0^2}{\omega^2} (\nabla \Phi_0)_\perp^2 = (\nabla \Phi_0)^2 \quad (\text{A.14})$$

which corresponds to gravity waves. Note that this relation has been obtained under the assumption that the Coriolis force is negligible. While justified for high frequency acoustic waves, this assumption is not necessarily true for gravity waves whose frequency is limited by N_O .

Finally, the next order of the expansion (A.11) yields the amplitude A_0 in terms of Φ_0 (see for example Lighthill (1978)).

Appendix B: Properties of the PSS

Two specific properties of the $r_p(\theta) = r_s(\theta) - d$ PSS are considered below. First, we check in the non-rotating case that the distance d can be chosen in order that all relevant trajectories intersect the $r_p(\theta) = r_s(\theta) - d$ curve. Second, we define a coordinate system of the PSS which ensures that any surface of the PSS is conserved by the dynamics.

B.1. Choice of the distance to the stellar surface

In the non-rotating case, equation (21) enables to characterize the trajectories that do not cross the PSS for a given value of d , the distance to the stellar surface. The radius of the internal caustic of these trajectories r_i must be such that $r_i > r_p$. Using the definition of r_i and assuming that $\omega \gg \omega_c(r_i)$, implies that $\tilde{L} > r_p/c_s(r_p)$. According to the relation between \tilde{L} and ℓ the degree of the corresponding mode $\tilde{L} = (\ell + 1/2)/\omega$ (see Eq. (23) in subsection 4.1), we find that these trajectories are associated with high degree modes ($\ell > 136$) for the chosen value of $d = 0.08R_e$ and for $\omega = 8.4\omega_1$, where ω_1 is the lowest acoustic mode frequency of the stellar model considered. These modes are thus irrelevant for asteroseismology since their amplitude strongly cancels out when integrated over the visible disk.

B.2. Area-preserving coordinates of the PSS

The PSS being defined by $r_p(\theta) = r_s(\theta) - d$, we show here that θ , the colatitude, and $\tilde{k}_\theta = k_\theta/\omega$, k_θ the angular component of \mathbf{k} in the natural basis associated with the coordinate system $[\zeta = r_s(\theta) - r, \theta, \phi]$, are area-preserving coordinates of the PSS.

First we show that, for a general coordinate system x_i , the spatial coordinates x_i and the covariant component \tilde{k}_i of the vector $\tilde{\mathbf{k}}$ in the natural basis are conjugate variables of the Hamiltonian H given by Eq. (17). The natural basis associated to a coordinate system x_i is defined by $(\mathbf{E}_1, \mathbf{E}_2, \mathbf{E}_3)$ where $\mathbf{E}_i = \partial \mathbf{x} / \partial x^i$. The contravariant component \tilde{k}^i of the velocity $\tilde{\mathbf{k}} = \dot{\mathbf{x}}$ thus verify $\dot{x}_i = \tilde{k}^i$ (the notation \dot{x}_i denotes a derivative with respect to the time-like coordinate t). If $L(\dot{\mathbf{x}}, \mathbf{x}, t)$ is the Lagrangian of a system expressed in a coordinate system x_i , it is well known that a Legendre transformation enables to construct a Hamiltonian $H = \sum \dot{x}_i \partial L / \partial \dot{x}_i - L$ where $p_i = \partial L / \partial \dot{x}_i$ is conjugate to x_i . The Lagrangian $L = \frac{\tilde{\mathbf{k}}^2}{2} - W(\mathbf{x})$ being associated with the Hamiltonian H given by Eq. (17), the momentum variable p_i can be simply computed:

$$p_i = \frac{\partial L}{\partial \dot{x}_i} = \frac{1}{2} \frac{\partial \tilde{\mathbf{k}} \cdot \tilde{\mathbf{k}}}{\partial \tilde{k}^i} = \tilde{\mathbf{k}} \cdot \frac{\partial \tilde{\mathbf{k}}}{\partial \tilde{k}^i} = \tilde{\mathbf{k}} \cdot \mathbf{E}_i = \tilde{k}_i \quad (\text{B.1})$$

thus showing that $[x_i, \tilde{k}_i]$ are conjugate variables of H .

Moreover, for a given conjugate coordinate system $[x_i, p_i]$, the coordinates $[x_2, x_3, p_2, p_3]$ of the PSS defined by $x_1 = \text{const}$ are known to be area-preserving (Ott, 1993). Thus, in our case, $[\zeta, \theta, \tilde{k}_\zeta, \tilde{k}_\theta]$ is a conjugate coordinate system for the reduced

Hamiltonian H_r and the system $[\theta, \tilde{k}_\theta]$ is area-preserving for the PSS $\zeta = \text{const}$. Note that the natural basis and its conjugate reads $\mathbf{E}_\zeta = -\mathbf{e}_r, \mathbf{E}_\theta = (dr_s/d\theta) \mathbf{e}_r + r_p \mathbf{e}_\theta$ and $\mathbf{E}^\zeta = -\mathbf{e}_r + [(dr_s/d\theta)/r_p] \mathbf{e}_\theta, \mathbf{E}^\theta = (1/r_p) \mathbf{e}_\theta$ in terms of the unit vector associated with the spherical coordinates $(\mathbf{e}_r, \mathbf{e}_\theta)$. Thus, with respect to the wavevector components in spherical coordinates $\tilde{k}_r^{sph}, \tilde{k}_\theta^{sph}$, the \tilde{k}_θ component reads $\tilde{k}_\theta = (dr_s/d\theta) \tilde{k}_r^{sph} + r_p \tilde{k}_\theta^{sph}$.

Appendix C: Calculation of phase space volumes

Following the Monte-Carlo quadrature method (Press et al., 1992), N_S points are randomly chosen in a known volume V_S that includes the volume V to be computed. The proportion of points inside V approximates the ratio V/V_S , thus providing an estimated value of V . The standard deviation error yields an estimate of the relative error, $\sqrt{(V_M/V - 1)/N_S}$, showing that the sampling volume V_S has to be as close as possible to the volume V and that the number of sampling points must be large.

In our case, the main practical issue is thus to determine if a given point in phase space is inside or outside the 4-dimensional volume to be computed. The two volumes that we have computed are specified by two limiting frequencies $9.42\omega_1 \leq H'_r(\mathbf{x}, \mathbf{k}) \leq 11.85\omega_1$ and for each value of H'_r by the 3D volume inside a given 2D torus. The first torus considered separates the whispering gallery region from the chaotic region, its imprint on the $r = r_p$ PSS being shown on Fig. C.1. The volume inside this torus includes the large chaotic region as well as the island chains around the 2-period and 6-period orbits. The second volume corresponds to the 2-period island chain and is delimited by a torus also shown on Fig. C.1.

To determine whether a given point $\mathbf{x}_0, \mathbf{k}_0$ is inside or outside these volumes, one could construct the $r = r_p$ PSS associated to the value of the Hamiltonian $H'_r(\mathbf{x}_0, \mathbf{k}_0)$, advance the dynamics from $\mathbf{x}_0, \mathbf{k}_0$ until the trajectory cross the $r = r_p$ PSS and find out whether the crossing point is inside or outside the torus. Here, to simplify the procedure, we used the fact that the $r = r_p$ PSS plotted against the scaled wavenumber $\tilde{\mathbf{k}}$ appeared to be insensitive to values of the frequency ω in the domain considered. We thus consider the point $\mathbf{x}_0, \mathbf{k}_0/H'_r(\mathbf{x}_0, \mathbf{k}_0)$ and determine its location in the scaled phase space computed for a given frequency. To control this supposedly small frequency effect the computation has been performed for the two extreme frequencies $\omega = 9.42\omega_1$ and $\omega = 11.85\omega_1$. Moreover, instead of advancing the dynamics up to the $r = r_p$ PSS, we construct a local PSS (either from a $\zeta = \text{const}$ surface or a $\tilde{k}_\zeta = \text{const}$ surface) to compare the location of the $\mathbf{x}_0, \mathbf{k}_0$ point with the local imprint of the delimiting torus. In practice, the imprint of the delimiting torus is not a continuous curve as the torus is actually obtained from a space filling trajectory on the torus. We therefore follow such a trajectory over a sufficiently large number of time step to increase the number of point of the torus imprint on the different PSS. This procedure has been tested using trajectories which are known to be either inside or outside the torus (like for example trajectories on nested tori inside the 2-period island chain). The number of points wrongly located by this procedure can be made small enough to have a negligible effect when compared to the statistical error on the volume determination. Furthermore, the integration domain has been divided in three sub-domains following the pseudo-radial direction ζ . This enables to limit the ratio V/V_S as the sampling volumes can be more easily reduced in each sub-domain.

Accordingly the number of modes within the 2-period island chain is 33 ± 1 if we use the bounding torus computed for $\omega =$

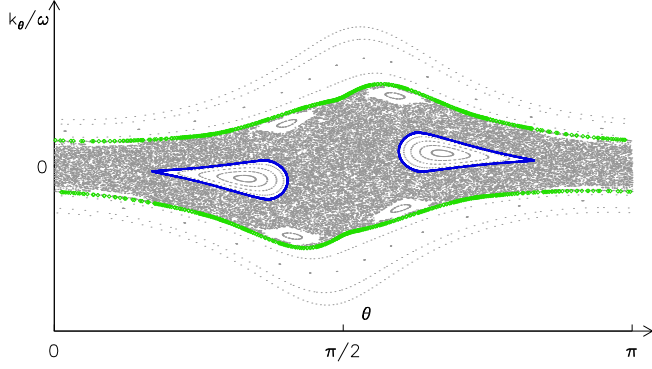


Fig. C.1. (Color online) Intersection of two trajectories with the PSS at $\Omega = 0.59\Omega_K$. The crosses (blue) correspond to a trajectory on a torus containing most of the 2-period island chain. The diamonds (green) correspond to a trajectory on a torus bounding the central chaotic region.

$9.42\omega_1$ and 34 ± 1 for $\omega = 11.85\omega_1$. The effect of changing the frequency is small in this case and the number of modes can be estimated to 34 ± 2 . Likewise, the number of modes outside the whispering gallery region is 263 ± 1 for $\omega = 9.42\omega_1$ bounding torus and 276 ± 2 for $\omega = 11.85\omega_1$. The frequency effect is larger but still reasonable for the present purpose. We took the mean value of 270 modes with an error of ± 8 mode.

Appendix D: Calculation of the disk-integration factor

According to the definition of the disk-integration factor, Eq. (37), we are led to calculate integrals of the following form:

$$I = \iint_{S_v} F(\theta, \phi) d\mathbf{S} \cdot \mathbf{e}_i \quad (\text{D.1})$$

$$= \iint_{S_v} G(\theta, \phi, i) d\mu d\phi \quad (\text{D.2})$$

where $\mu = \cos \theta$ and $F(\theta, \phi) = W(\theta)e^{im\phi}$ is the surface distribution of the eigenfunction. The spherical coordinate system $[r, \theta, \phi]$ is such that the polar axis is the rotation axis, and the meridional plane $\phi = 0$ is chosen parallel to \mathbf{e}_i . The condition $d\mathbf{S} \cdot \mathbf{e}_i = 0$ on the stellar surface defines a curve which separates the visible part of the surface S_v from the invisible one (the surface is supposed to be convex). We call this curve the visibility curve.

We used two methods to compute the integral I . The first one is approximate as it assumes that the visibility curve is contained in a plane but it is easy to compute accurately. The second method does not make this assumption but requires more computing time to complete accurate calculations.

The vector $d\mathbf{S}$ at the star's surface reads:

$$d\mathbf{S} = \sin \theta r_s \left(r_s^2 + \left(\frac{dr_s}{d\theta} \right)^2 \right)^{1/2} \mathbf{e}^s d\theta d\phi \quad (\text{D.3})$$

where \mathbf{e}^s denotes the unit vector perpendicular to the surface and $r_s(\theta)$ is the stellar surface. Thus, the function to integrate can be written as:

$$F(\theta, \phi) d\mathbf{S} \cdot \mathbf{e}_i = A(\theta) \sin \theta \cos i e^{im\phi} - B(\theta) \sin \theta \sin i \cos \phi e^{im\phi} \quad (\text{D.4})$$

where

$$A = r_s \frac{d}{d\theta} (r_s \sin \theta) W(\theta) \quad (\text{D.5})$$

$$B = r_s \frac{d}{d\theta} (r_s \cos \theta) W(\theta) \quad (\text{D.6})$$

D.1. First method

The colatitude verifying $d\mathbf{S} \cdot \mathbf{e}_i = 0$ for $\phi = 0$ is denoted $\theta_L(i)$. As the inclination angle i can be restricted to $[0, \pi/2]$, we have $\pi/2 < \theta_L(i) < \pi$ and the angle α defined as $\alpha(i) = \theta_L(i) - \pi/2$ verifies $0 < \alpha(i) < \pi/2$. We assume that the visibility curve is the intersection of the stellar surface with the plane $\sin \alpha x + \cos \alpha z = 0$, where the vector \mathbf{e}_α of Cartesian coordinates $(\sin \alpha, 0, \cos \alpha)$ is normal to this plane.

Then, the integral is most simply calculated in the coordinate system in which the polar axis is aligned with the direction of the vector \mathbf{e}_α . This coordinate system results from a rotation of angle α around the y axis of the original coordinate system, the new angular variables being denoted θ' and ϕ' .

To express the integrand in these coordinates, we use the formula relating the spherical harmonics in both systems:

$$Y_\ell^m(\theta, \phi) = \sum_{m'=-\ell}^{+\ell} d_{\ell m m'}^\ell(\alpha) Y_\ell^{m'}(\theta', \phi') \quad (\text{D.7})$$

where $d_{\ell m m'}^\ell(\alpha)$ do not generally have a simple form (Edmonds 1960). Then, using the spherical harmonic expansion of G , we obtain:

$$G = \sum_{\ell=0}^{+\infty} \sum_{m=-\ell}^{+\ell} G_\ell^m(i) Y_\ell^m(\theta, \phi) \quad (\text{D.8})$$

$$= \sum_{\ell=0}^{+\infty} \sum_{m=-\ell}^{+\ell} \sum_{m'=-\ell}^{+\ell} G_\ell^m(i) d_{\ell m m'}^\ell(\alpha) Y_\ell^{m'}(\theta', \phi') \quad (\text{D.9})$$

Then, integrating over the longitude ϕ' , from 0 to 2π , the terms involving $Y_\ell^{m'}(\theta', \phi')$ vanish if $m' \neq 0$. It follows that

$$I = 2\pi \sum_{\ell=0}^{+\infty} \sum_{m=-\ell}^{+\ell} J_\ell G_\ell^m(i) \hat{Y}_\ell^m(\alpha) \quad (\text{D.10})$$

where we used the following relations,

$$d_{\ell m 0}^\ell(\alpha) = \sqrt{\frac{4\pi}{2\ell+1}} \hat{Y}_\ell^m(\alpha) \quad (\text{D.11})$$

$$d\mu d\phi = d\mu' d\phi' \quad \text{where } \mu' = \cos \theta' \quad (\text{D.12})$$

and defined J_ℓ as,

$$J_\ell = \sqrt{\frac{4\pi}{2\ell+1}} \int_0^1 \hat{Y}_\ell^0(\mu') d\mu' \quad (\text{D.13})$$

$$= \begin{cases} 0 & \text{if } \ell \text{ is even and } \ell \neq 0, \\ 1 & \text{if } \ell = 0, \\ (-1)^{\frac{\ell-1}{2}} \frac{1.3 \dots (\ell-2)}{2.4 \dots (\ell+1)} & \text{if } \ell \text{ is odd and } \ell \neq 1, \\ \frac{1}{2} & \text{if } \ell = 1. \end{cases} \quad (\text{D.14})$$

To determine the coefficients $G_\ell^m(i)$, we use the expression of G derived from Eq. (D.4):

$$G = A(\theta) \cos i e^{im\phi} - B(\theta) \sin i \cos \phi e^{im\phi} \quad (\text{D.15})$$

It follows that

$$G_k^\ell = 0 \text{ if } k \neq m-1, m, m+1 \quad (\text{D.16})$$

so that the integral now reads:

$$I/2\pi = I_{m-1} + I_m + I_{m+1} \text{ where} \quad (\text{D.17})$$

$$I_m = \cos i \hat{A}_m(\alpha) \quad (\text{D.18})$$

$$I_{m-1} = -\frac{\sin i}{2} \hat{B}_{m-1}(\alpha) \quad (\text{D.19})$$

$$I_{m+1} = -\frac{\sin i}{2} \hat{B}_{m+1}(\alpha) \quad (\text{D.20})$$

where \hat{A}_m denotes:

$$\hat{A}_m(\alpha) = \sum_{\ell=|m|}^{+\infty} J_\ell A_m^\ell \hat{Y}_\ell^m(\alpha) \quad (\text{D.21})$$

$$A_m^\ell = 2\pi \int_0^\pi A(\theta) \hat{Y}_\ell^m(\theta) \sin \theta d\theta \quad (\text{D.22})$$

the \hat{B}_m terms being defined accordingly.

Note that for modes which are equatorially anti-symmetric and axisymmetric ($m = 0$), $\hat{A}_0(\alpha) = J_0 A_0^0 \hat{Y}_0^0(\alpha)$ and $\hat{B}_1(\alpha) = \hat{B}_{-1}(\alpha) = 0$, thus the integral I reduces to:

$$I = 4\pi \sqrt{\pi} A_0^0 \cos(i). \quad (\text{D.23})$$

D.2. Second method

The visibility curve is no longer assumed to be planar. The integration over the visible surface is first performed in the azimuthal direction and then in latitude. If $0 \leq \theta \leq \pi/2 - \alpha$, the integration is made between 0 and 2π , while in the interval $\pi/2 - \alpha \leq \theta \leq \pi/2 + \alpha$ one has to integrate between the two limiting azimuths $-\phi_L(\theta, i)$ and $\phi_L(\theta, i)$ verifying $\mathbf{dS} \cdot \mathbf{e}_i = 0$. The integration domain is thus divided in two sub-domains, such that

$$S_v = [0, \frac{\pi}{2} - \alpha] \times [0, 2\pi] \cup [\frac{\pi}{2} - \alpha, \frac{\pi}{2} + \alpha] \times [-\phi_L, \phi_L] \quad (\text{D.24})$$

According to Eq. (D.4), the integration over ϕ can be made analytically as it involves quadratures of $e^{im\phi}$ and $\cos \phi e^{im\phi}$ over $[0, 2\pi]$ and $[-\phi_L, \phi_L]$. Then, depending on the value of m , the integral I reads:

$$I = \begin{cases} 2\pi \int_0^{\frac{\pi}{2}-\alpha} a d\theta + 2 \int_{\frac{\pi}{2}-\alpha}^{\frac{\pi}{2}+\alpha} a \phi_L - b \sin(\phi_L) d\theta & \text{if } m = 0 \\ -\pi \int_0^{\frac{\pi}{2}-\alpha} b d\theta + \int_{\frac{\pi}{2}-\alpha}^{\frac{\pi}{2}+\alpha} 2a \sin(\phi_L) - b \left(\phi_L + \frac{1}{2} \sin(2\phi_L) \right) d\theta & \text{if } m = \pm 1 \\ \int_{\frac{\pi}{2}-\alpha}^{\frac{\pi}{2}+\alpha} \frac{2a}{m} \sin(m\phi_L) - b \left(\frac{\sin[(m+1)\phi_L]}{m+1} + \frac{\sin[(m-1)\phi_L]}{m-1} \right) d\theta & \text{if } m \neq 0, \pm 1. \end{cases} \quad (\text{D.25})$$

where $a(\theta, i) = A(\theta) \sin \theta \cos i$ and $b(\theta, i) = B(\theta) \sin \theta \sin i$.

D.3. Tests

The methods have been tested in the case of an uniformly distributed function on the surface of an ellipsoid where they should both give the same result. Then, the error introduced by the approximation of method 1 is estimated in the case of a Roche model surface.

D.3.1. Ellipsoid

The surface being a quadric, the visibility curve is planar. Method 1 is therefore exact and should give the same result as method 2. In addition, the visible surface (obtained by taking $F = 1$) can be obtained analytically. Indeed, the dimensionless equation of the ellipsoid is:

$$x^2 + y^2 + \frac{z^2}{\tilde{R}_p^2} = 1 \quad (\text{D.26})$$

and in spherical coordinates:

$$r = \frac{1}{\sqrt{1 + \frac{1-\tilde{R}_p^2}{\tilde{R}_p^2} \cos^2 \theta}} \quad (\text{D.27})$$

where the distance have been normalized by the equatorial radius R_e and $\tilde{R}_p = R_p/R_e$. As \mathbf{dS} is parallel to $(2x, 2y, 2z/\tilde{R}_p^2)$ and $\mathbf{e}_i = (\sin i, 0, \cos i)$, surface points verifying $\mathbf{dS} \cdot \mathbf{e}_i = 0$ belong to the plane:

$$x \sin i + \frac{z \cos i}{\tilde{R}_p^2} = 0 \quad (\text{D.28})$$

By definition of the angle α , we have

$$\tan \alpha = \tilde{R}_p^2 \tan i \quad (\text{D.29})$$

In addition, using Eq. (D.28) and the relation between the Cartesian and spherical coordinates, the equation of the intersection between the plane $x \sin i + (z \cos i)/\tilde{R}_p^2 = 0$ and the ellipsoid is given by Eq. (D.27) and

$$\cos \phi_L = -\frac{\cot \theta \cot i}{\tilde{R}_p^2} = -\cot \theta \cot \alpha \quad (\text{D.30})$$

Thus,

$$\phi_L(\theta, i) = \arccos(-\cot \theta \cot \alpha) \quad (\text{D.31})$$

is defined if $\pi/2 - \alpha \leq \theta \leq \pi/2 + \alpha$ and verifies $0 \leq \phi_L \leq \pi$.

The visible surface can be calculated analytically as the visible curve is an ellipse. This can be seen using the Cartesian coordinates obtained by the rotation of angle α about the Oy axis:

$$x' = \cos \alpha x - \sin \alpha z \quad (\text{D.32})$$

$$y' = y \quad (\text{D.33})$$

$$z' = \sin \alpha x + \cos \alpha z \quad (\text{D.34})$$

The curve is then contained in the plane $z' = 0$ and verifies:

$$(\cos^2 \alpha + \frac{\sin^2 \alpha}{\tilde{R}_p^2}) x'^2 + y'^2 = 1 \quad (\text{D.35})$$

The surface of this ellipse can be calculated as well as its projection in the direction \mathbf{e}_i , denoted S_v^p :

$$S_v^p/R_e^2 = \pi \cos(\alpha - i) \sqrt{\frac{1 + \tan^2 i \tilde{R}_p^4}{1 + \tan^2 i \tilde{R}_p^2}} \quad (\text{D.36})$$

$$= \pi \cos i \sqrt{1 + \tan^2 i \tilde{R}_p^2} \quad (\text{D.37})$$

Both method were successfully tested against this analytical expression. Method 1 is simpler as it does not require a numerical integration. It is also very accurate although, if one wants to reach machine precision, it is necessary to use the analytical value of θ_L .

D.3.2. Method 1 versus Method 2

Method 1 is approximate as it assumes that the curve on the surface verifying $\mathbf{dS} \cdot \mathbf{e}_i = 0$ is planar and contained in the plane $\sin \alpha x + \cos \alpha z = 0$. Nevertheless, the associated error is not expected to be large as it concerns a small part of the whole visible surface. To test this, we simply compute the integral for $F = 1$ with both methods for a surface given by a Roche model of rotating star. Method 2 computes the projected visible surface while the quantity calculated by method 1 is smaller as the integration includes a region where $\mathbf{dS} \cdot \mathbf{e}_i < 0$ and excludes a visible region of equivalent surface which is symmetrical with respect to the star center. The difference between the two quantities can be also calculated by directly computing the integral:

$$2 \int_{\frac{\pi}{2}}^{\frac{\pi}{2}+\alpha} a\phi_L - b \sin(\phi_L) d\theta \quad (\text{D.38})$$

using either the correct value of ϕ_L or the one corresponding to the assumption of method 1, that is

$$\cos \phi'_L = -\cot \theta \cot \alpha \quad (\text{D.39})$$

In Fig. D.1, the relative error on the projected visible surface due to method 1 is plotted for Roche model surfaces of different flatness.

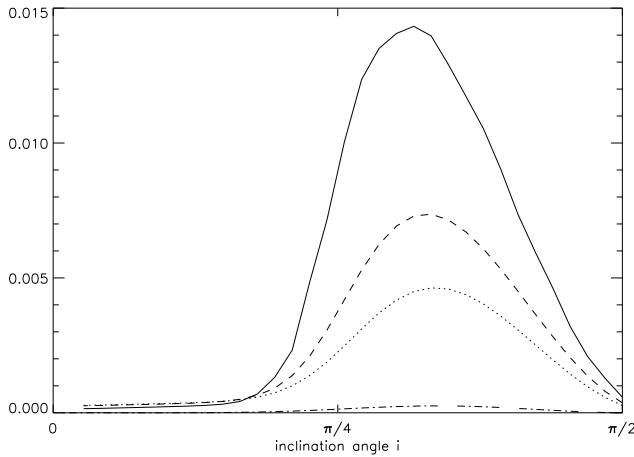


Fig. D.1. Relative error of the projected visible surface computed with method 1 for Roche models of different flatness : 0.1526 (dot-dashed), 0.2594 (dotted) 0.2804 (dashed), 0.3092 (continuous line).

It appears that, except for the near critical values of the flatness, the visible surface that is not considered by method 1 is a very small fraction of the total visible surface. Using method 1 is therefore a good approximation in these cases. For near critical flatness, the difference remains small although it can be useful to test results of method 1 with method 2.